

# Package ‘SpatialExtremes’

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**Depends** R (>= 1.8.0)

**Description** This package proposes several approaches for spatial extremes modelling.

**License** GPL (>= 2)

**URL** <http://spatialextremes.r-forge.r-project.org/>

**Archs** i386, x86\_64

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 anova

*Anova Tables*


---

## Description

Computes analysis of deviance for objects of class "maxstab"

## Usage

```
## S3 method for class 'maxstab'
anova(object, object2, method = "RJ", square = "chol",
      ...)
## S3 method for class 'spatgev'
anova(object, object2, method = "RJ", square = "chol",
      ...)
```

**Arguments**

<code>object, object2</code>	Two objects of class 'maxstab' or 'spatgev'.
<code>method</code>	Character string. Must be one of "CB" or "RJ" for the Chandler and Bate or the Rotnitzky and Jewell approaches respectively. See function <a href="#">profile</a> .
<code>square</code>	The choice for the matrix square root. This is only useful for the 'CB' method. Must be one of 'chol' (Cholesky) or 'svd' (Singular Value Decomposition).
<code>...</code>	Other options to be passed to the <a href="#">anova</a> function.

**Details**

As "maxstab" objects are fitted using pairwise likelihood, the model is misspecified. As a consequence, the likelihood ratio statistic is no longer  $\chi^2$  distributed. To compute the anova table, we use the methodology proposed by Rotnitzky and Jewell to adjust the distribution of the likelihood ratio statistic.

**Value**

This function returns an object of class anova. These objects represent analysis-of-deviance tables.

**Author(s)**

Mathieu Ribatet

**References**

- Chandler, R. E. and Bate, S. (2007) Inference for clustered data using the independence loglikelihood *Biometrika*, **94**, 167–183.
- Rotnitzky, A. and Jewell, N. (1990) Hypothesis testing of regression parameters in semiparametric generalized linear models for cluster correlated data. *Biometrika* **77**, 485–497.

**See Also**

[fitmaxstab](#), [fitspatgev](#), [profile](#), [TIC](#)

**Examples**

```
##Define the coordinates of each location
n.site <- 30
locations <- matrix(rnorm(2*n.site, sd = sqrt(.2)), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 100, cov12 =
25, cov22 = 220)

##Now define the spatial model for the GEV parameters
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1] + locations[,2]^2
param.shape <- rep(0.2, n.site)

##Transform the unit Frechet margins to GEV
for (i in 1:n.site)
```

```

data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

##Define three models for the GEV margins to be fitted
loc.form <- loc ~ lat
scale.form <- scale ~ lon + I(lat^2)
shape.form <- shape ~ lon

M0 <- fitspatgev(data, locations, loc.form, scale.form, shape.form)
M1 <- fitspatgev(data, locations, loc.form, scale.form, shape.form,
shapeCoeff2 = 0)

##Model selection
anova(M0, M1)
anova(M0, M1, method = "CB", square = "svd")

```

---

condmap

*Produces a conditional 2D map from a fitted max-stable process*


---

## Description

Produces a conditional 2D map from a fitted max-stable process.

## Usage

```

condmap(fitted, fix.coord, x, y, covariates = NULL, ret.per1 = 100,
ret.per2 = ret.per1, col = terrain.colors(64), plot.contour = TRUE,
...)
```

## Arguments

<code>fitted</code>	An object of class <code>maxstab</code> . Most often, it will be the output of the function <code>fitmaxstab</code> .
<code>fix.coord</code>	The spatial coordinates of the location from which the conditional quantile is computed.
<code>x, y</code>	Numeric vector defining the grid at which the levels are computed.
<code>covariates</code>	An array specifying the covariates at each grid point defined by <code>x</code> and <code>y</code> . If <code>NULL</code> , no covariate is needed. See <code>map</code> to see how to build it.
<code>ret.per1, ret.per2</code>	Numerics giving the return period for which the quantile map is plotted. See details.
<code>col</code>	A list of colors such as that generated by <code>'rainbow'</code> , <code>'heat.colors'</code> , <code>'topo.colors'</code> , <code>'terrain.colors'</code> or similar functions.
<code>plot.contour</code>	Logical. If <code>TRUE</code> (default), contour lines are added to the plot.
<code>...</code>	Several arguments to be passed to the <code>image</code> function.

**Details**

The function solves the following equation:

$$\Pr [Z(x_2) > z_2 | Z(x_1) > z_1] = \frac{1}{T_2}$$

where  $z_1 = -1/\log(1 - 1/T_1)$ .

In other words, it computes, given that at location  $x_1$  we exceed the level  $z_1$ , the levels which is expected to be exceeded in average every  $T_2$  year.

**Value**

A plot. Additionally, a list with the details for plotting the map is returned invisibly.

**Author(s)**

Mathieu Ribatet

**See Also**

[map](#), [filled.contour](#), [heatmap](#), [heat.colors](#), [topo.colors](#), [terrain.colors](#), [rainbow](#)

**Examples**

```
##Define the coordinate of each location
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "whitmat", sill = 1, range =
2, smooth = 1)

##Now define the spatial model for the GEV parameters
param.loc <- -10 - 4 * locations[,1] + locations[,2]^2
param.scale <- 5 + locations[,2] + locations[,1]^2 / 10
param.shape <- rep(.2, n.site)

##Transform the unit Frechet margins to GEV
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

##Define a model for the GEV margins to be fitted
##shape ~ 1 stands for the GEV shape parameter is constant
##over the region
loc.form <- loc ~ lon + I(lat^2)
scale.form <- scale ~ lat + I(lon^2)
shape.form <- shape ~ 1

## 1- Fit a max-stable process
fitted <- fitmaxstab(data, locations, "whitmat", loc.form, scale.form,
shape.form, sill = 1, std.err.type = "none")
```

```
cond.coord <- c(5.1, 5.1)
condmap(fitted, cond.coord, seq(0, 10, length = 25), seq(0,10, length
=25), ret.per1 = 100, ret.per2 = 1.5)
points(t(cond.coord), pch = "*", col = 2, cex = 2)
```

---

condrgp

*Conditional simulation of Gaussian random fields*


---

### Description

This function generates conditional simulation of Gaussian random fields from the simple kriging predictor.

### Usage

```
condrgp(n, coord, data.coord, data, cov.mod = "powexp", mean = 0, nugget
= 0, sill = 1, range = 1, smooth = 1, grid = FALSE, control = list())
```

### Arguments

n	Integer. The number of conditional simulations.
coord	A numeric vector or matrix specifying the coordinates where the process has to be generated. If coord is matrix, each row specifies one location.
data.coord	A numeric vector or matrix specifying the coordinates where the process is conditioned.
data	A numeric vector giving the conditioning observations.
cov.mod	A character string specifying the covariance function family. Must be one of "whitmat", "powexp", "cauchy" or "bessel" for the Whittle-Mater, the powered exponential, the Cauchy or Bessel covariance families.
mean, nugget, sill, range, smooth	The mean, nugget, sill, range and smooth of the Gaussian process.
grid	Logical. Does coord specifies a grid?
control	A named list passing options to the simulation method of Gaussian processes — see <a href="#">rgp</a> .

### Value

A list with components:

coord	The coordinates at which the process was simulated;
cond.sim	The simulated process;
data.coord	The coordinates of the conditioning locations;
data	The conditioning observations;
cov.mod	The covariance function family;
grid	Does coord specifies a grid?

### Author(s)

Mathieu Ribatet

**See Also**

[kriging](#), [rgp](#).

**Examples**

```
## Several conditional simulations
n.site <- 50
n.sim <- 512

x.obs <- runif(n.site, -100, 100)
x.sim <- seq(-100, 100, length = n.sim)

data <- rgp(1, x.obs, "whitmat", sill = 1, range = 10, smooth = 0.75)

sim <- condrgp(5, x.sim, x.obs, data, "whitmat", sill = 1, range =
10, smooth = 0.75)

matplot(x.sim, t(sim$cond.sim), type = "l", lty = 1, xlab = "x", ylab =
expression(Y[cond](x)))
points(x.obs, data, pch = 21, bg = 1)
title("Five conditional simulations")

## Comparison between one conditional simulations and the kriging
## predictor on a grid
x.obs <- matrix(runif(2 * n.site, -100, 100), ncol = 2)
x <- y <- seq(-100, 100, length = 100)
x.sim <- cbind(x, y)

data <- rgp(1, x.obs, "whitmat", sill = 1, range = 50, smooth = 0.75)

krig <- kriging(data, x.obs, x.sim, "whitmat", sill = 1, range = 50,
smooth = 0.75, grid = TRUE)
sim <- condrgp(1, x.sim, x.obs, data, "whitmat", sill = 1, range = 50,
smooth = 0.75, grid = TRUE)

z.lim <- range(c(sim$cond.sim, data, krig$krig.est))
breaks <- seq(z.lim[1], z.lim[2], length = 65)
col <- heat.colors(64)
idx <- as.numeric(cut(data, breaks))

op <- par(mfrow = c(1,2))
image(x, y, krig$krig.est, col = col, breaks = breaks)
points(x.obs, bg = col[idx], pch = 21)
title("Kriging predictor")
image(x, y, sim$cond.sim, col = col, breaks = breaks)
points(x.obs, bg = col[idx], pch = 21)
title("Conditional simulation")
## Note how the background colors of the above points matches the ones
## returned by the image function
par(op)
```

## Description

This function defines and computes several covariance function either from a fitted “max-stable” model; either by specifying directly the covariance parameters.

## Usage

```
covariance(fitted, sill, range, smooth, smooth2 = NULL, cov.mod =
"whitmat", plot = TRUE, dist, xlab, ylab, ...)
```

## Arguments

<code>fitted</code>	An object of class “maxstab”. Most often this will be the output of the <code>fitmaxstab</code> function. May be missing if <code>sill</code> , <code>range</code> , <code>smooth</code> and <code>cov.mod</code> are given.
<code>sill, range, smooth, smooth2</code>	The sill, scale and smooth parameters for the covariance function. May be missing if <code>fitted</code> is given.
<code>cov.mod</code>	Character string. The name of the covariance model. Must be one of "whitmat", "cauchy", "powexp", "bessel" or "caugen" for the Whittle-Matern, Cauchy, Powered Exponential, Bessel and Generalized Cauchy models. May be missing if <code>fitted</code> is given.
<code>plot</code>	Logical. If TRUE (default) the covariance function is plotted.
<code>dist</code>	A numeric vector corresponding to the distance at which the covariance function should be evaluated. May be missing.
<code>xlab, ylab</code>	The x-axis and y-axis labels. May be missing.
<code>...</code>	Several option to be passed to the <code>plot</code> function.

## Details

Currently, four covariance functions are defined: the Whittle-Matern, powered exponential (also known as "stable"), Cauchy and Bessel models. These covariance functions are defined as follows:

$$\textbf{Whittle-Matern } \rho(h) = sill \frac{2^{1-smooth}}{\Gamma(smooth)} \left(\frac{h}{range}\right)^{smooth} K_{smooth} \left(\frac{h}{range}\right)$$

$$\textbf{Powered Exponential } \rho(h) = sill \exp \left[ - \left(\frac{h}{range}\right)^{smooth} \right]$$

$$\textbf{Cauchy } \rho(h) = sill \left[ 1 + \left(\frac{h}{range}\right)^2 \right]^{-smooth}$$

$$\textbf{Bessel } \rho(h) = sill \left(\frac{2range}{h}\right)^{smooth} \Gamma(smooth + 1) J_{smooth} \left(\frac{h}{range}\right)$$

$$\textbf{Generalized Cauchy } \rho(h) = sill \left\{ 1 + \left(\frac{h}{range}\right)^{smooth2} \right\}^{-smooth/smooth2}$$

where  $\Gamma$  is the gamma function,  $K_{smooth}$  and  $J_{smooth}$  are both modified Bessel functions of order  $smooth$ .

## Value

This function returns the covariance function. Eventually, if `dist` is given, the covariance function is computed for each distance given by `dist`. If `plot = TRUE`, the covariance function is plotted.

**Author(s)**

Mathieu Ribatet

**Examples**

```
## 1- Calling covariance using fixed covariance parameters
covariance(sill = 1, range = 1, smooth = 0.5, cov.mod = "whitmat")
covariance(sill = 0.5, range = 1, smooth = 0.5, cov.mod = "whitmat",
  dist = seq(0,5, 0.2), plot = FALSE)

## 2- Calling covariance from a fitted model
##Define the coordinate of each location
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(30, locations, cov.mod = "whitmat", sill = 1, range =
3, smooth = 1)

##Fit a max-stable model
fitted <- fitmaxstab(data, locations, "whitmat", std.err.type = "none",
sill = 1)
covariance(fitted, ylim = c(0, 1))
covariance(sill = 1, range = 3, smooth = 1, cov.mod = "whitmat", add =
TRUE, col = 3)
title("Whittle-Matern covariance function")
legend("topright", c("Theo.", "Fitted"), lty = 1, col = c(3,1), inset =
.05)
```

cv

*Estimates the penalty coefficient from the cross-validation criterion***Description**

Estimates the penalty coefficient from the cross-validation criterion.

**Usage**

```
cv(y, x, knots, degree, plot = TRUE, n.points = 150, ...)
```

**Arguments**

<code>y</code>	The response vector.
<code>x</code>	A vector/matrix giving the values of the predictor variable(s). If <code>x</code> is a matrix, each row corresponds to one observation.
<code>knots</code>	A vector giving the coordinates of the knots.
<code>degree</code>	The degree of the penalized smoothing spline.
<code>plot</code>	Logical. If TRUE (default), the evolution of the CV score as the penalty increases is plotted.
<code>n.points</code>	A numeric giving the number of CV computations needed to produce the plot.
<code>...</code>	Options to be passed to the <code>nlm</code> function.

**Details**

For every linear smoother e.g.  $\hat{y} = S_\lambda y$ , the cross-validation criterion consists in minimizing the following quantity:

$$CV(\lambda) = \sum_{i=1}^n \left( \frac{y_i - \hat{y}_i}{1 - S_{\lambda,ii}} \right)^2$$

where  $\lambda$  is the penalty coefficient,  $n$  the number of observations and  $S_{\lambda,ii}$  the  $i$ -th diagonal element of the matrix  $S_\lambda$ .

**Value**

A list with components 'penalty', 'cv' and 'nlm.code' which give the location of the minimum, the value of the cross-validation criterion at that point and the code returned by the `link{nlm}` function - useful to assess for convergence issues.

**Author(s)**

Mathieu Ribatet

**References**

Ruppert, D. Wand, M.P. and Carroll, R.J. (2003) *Semiparametric Regression* Cambridge Series in Statistical and Probabilistic Mathematics.

**See Also**

[cv](#)

**Examples**

```
n <- 200
x <- runif(n)
fun <- function(x) sin(3 * pi * x)
y <- fun(x) + rnorm(n, 0, sqrt(0.4))
knots <- quantile(x, prob = 1:(n/4) / (n/4 + 1))
cv(y, x, knots = knots, degree = 3)
```

---

 DIC

---

*Deviance Information Criterion*


---

**Description**

This function computes the Deviance Information Criterion (DIC), and related quantities, which is a hierarchical modeling generalization of the Akaike Information Criterion. It is useful for Bayesian model selection.

**Usage**

```
DIC(object, ..., fun = "mean")
```

**Arguments**

object	An object of class <code>latent</code> — typically this will be the output of <code>latent</code> .
...	Optional arguments. Not implemented.
fun	A character string giving the name of the function to be used to summarize the Markov chain. The default is to consider the posterior mean.

**Details**

The deviance is

$$D(\theta) = -2 \log \pi(y | \theta),$$

where  $y$  are the data,  $\theta$  are the unknown parameters of the models and  $\pi(y | \theta)$  is the likelihood function. Thus the expected deviance, a measure of how well the model fits the data, is given by

$$\bar{D} = E_{\theta}[D(\theta)],$$

while the effective number of parameters is

$$p_D = \bar{D} - D(\theta^*),$$

where  $\theta^*$  is point estimate of the posterior distribution, e.g., the posterior mean. Finally the DIC is given by

$$\text{DIC} = p_D + \bar{D}.$$

In accordance with the AIC, models with smaller DIC should be preferred to models with larger DIC. Roughly speaking, differences of more than 10 might rule out the model with the higher DIC, differences between 5 and 10 are substantial.

**Value**

A vector of length 3 that returns the DIC, effective number of parameters `eNoP` and an estimate of the expected deviance `Dbar`.

**Author(s)**

Mathieu Ribatet

**References**

Spiegelhalter, D. J., Best, N. G., Carlin, B. P. and Van Der Linde, A. (2002) Bayesian measures of model complexity and fit. *Journal of the Royal Statistical Society: Series B* **64**, 583–639.

**See Also**

[AIC](#)

**Examples**

```
## Generate realizations from the model
n.site <- 15
n.obs <- 35
coord <- cbind(lon = runif(n.site, -10, 10), lat = runif(n.site, -10, 10))

gp.loc <- rgp(1, coord, "powexp", sill = 4, range = 20, smooth = 1)
gp.scale <- rgp(1, coord, "powexp", sill = 0.4, range = 5, smooth = 1)
```

```

gp.shape <- rgp(1, coord, "powexp", sill = 0.01, range = 10, smooth = 1)

locs <- 26 + 0.5 * coord[, "lon"] + gp.loc
scales <- 10 + 0.2 * coord[, "lat"] + gp.scale
shapes <- 0.15 + gp.shape

data <- matrix(NA, n.obs, n.site)
for (i in 1:n.site)
  data[,i] <- rgev(n.obs, locs[i], scales[i], shapes[i])

loc.form <- y ~ lon
scale.form <- y ~ lat
shape.form <- y ~ 1

hyper <- list()
hyper$sills <- list(loc = c(1,8), scale = c(1,1), shape = c(1,0.02))
hyper$ranges <- list(loc = c(2,20), scale = c(1,5), shape = c(1, 10))
hyper$smooths <- list(loc = c(1,1/3), scale = c(1,1/3), shape = c(1, 1/3))
hyper$betaMeans <- list(loc = rep(0, 2), scale = c(9, 0), shape = 0)
hyper$betaIcov <- list(loc = solve(diag(c(400, 100))),
                      scale = solve(diag(c(400, 100))),
                      shape = solve(diag(c(10), 1, 1)))

## We will use an exponential covariance function so the jump sizes for
## the shape parameter of the covariance function are null.
prop <- list(gev = c(2.5, 1.5, 0.3), ranges = c(40, 20, 20), smooths = c(0,0,0))
start <- list(sills = c(4, .36, 0.009), ranges = c(24, 17, 16), smooths
             = c(1, 1, 1), beta = list(loc = c(26, 0), scale = c(10, 0),
                                     shape = c(0.15)))

mc <- latent(data, coord, loc.form = loc.form, scale.form = scale.form,
            shape.form = shape.form, hyper = hyper, prop = prop, start = start,
            n = 500)

DIC(mc)

```

---

distance

*Computes distance between pairs of locations*

---

### Description

This function computes euclidean distance or distance vector for each pair of a set of spatial locations.

### Usage

```
distance(coord, vec = FALSE)
```

### Arguments

coord	A matrix representing the coordinates of each locations. Each row corresponds to one location.
vec	Logical. If FALSE (default), the euclidean distance is computed. Otherwise, “distance vectors” are returned.

**Value**

If `vec = FALSE`, this function returns a vector that gives the euclidean distance for each pair of locations. Otherwise, this is a matrix where each column correspond to one dimension - i.e. longitude, latitude, ...

**Author(s)**

Mathieu Ribatet

**See Also**

[dist](#)

**Examples**

```
coords <- cbind(seq(0, 10, by = 2), seq(10, 0, by = -2))
distance(coords)
distance(coords, vec = TRUE)
```

---

extcoeff

*Plots the extremal coefficient*

---

**Description**

Plots the extremal coefficient evolution as the coordinates evolves.

**Usage**

```
extcoeff(fitted, cov.mod, param, n = 200, xlab, ylab, ...)
```

**Arguments**

<code>fitted</code>	A object of class "maxstab". Most often, it will be the output of the function <a href="#">fitmaxstab</a> . If missing, then <code>cov.mod</code> and <code>param</code> should be supplied.
<code>cov.mod</code>	A character string corresponding the the covariance model in the max-stable representation. Must be one of "gauss" for the Smith's model; or "whitmat", "cauchy" or "powexp" for the Whittle-Matern, the Cauchy and the Powered Exponential covariance family with the Schlather's model. May be missing if <code>fitted</code> is given.
<code>param</code>	Numeric vector of length 3. The parameters for the Smith's or Schlather model - i.e. <code>c(cov11, cov12, cov22)</code> or <code>c(sill, range, smooth)</code> . Please respect this order.
<code>n</code>	Numeric. $n^2$ corresponds to the total number of estimated extremal coefficients for the contour plot.
<code>xlab, ylab</code>	The x-axis and y-axis labels. May be missing.
<code>...</code>	Several options to be passed to the <a href="#">contour</a> function.

**Value**

A plot.

**Author(s)**

Mathieu Ribatet

**See Also**[fitmaxstab](#)**Examples**

```
## 1- Random field generation
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

data <- rmaxstab(60, locations, cov.mod = "whitmat", sill = 1, range =
3, smooth = 1)

## 2- Fit a max-stable processes
schlather <- fitmaxstab(data, locations, "whitmat", sill = 1)

## 3- Plot the extremal coefficient
extcoeff(schlather)
```

fitcovariance

*Estimates the covariance function for the Schlather's model***Description**

Estimates the covariance function for the Schlather's model using non-parametric estimates of the pairwise extremal coefficients.

**Usage**

```
fitcovariance(data, coord, cov.mod, marge = "emp", control = list(),
..., start, weighted = TRUE)
```

**Arguments**

data	A matrix representing the data. Each column corresponds to one location.
coord	A matrix that gives the coordinates of each location. Each row corresponds to one location.
cov.mod	A character string corresponding to the covariance model in the Schlather's model. Must be one of "whitmat", "cauchy", "powexp", "bessel" or "caugen" for the Whittle-Matern, the Cauchy, the Powered Exponential, the Bessel and the Generalized Cauchy correlation families.
marge	Character string specifying how margins are transformed to unit Frechet. Must be one of "emp", "frech" or "mle" - see function <a href="#">fitextcoeff</a> .
control	The control arguments to be passed to the <a href="#">optim</a> function.
...	Optional arguments to be passed to the <a href="#">optim</a> function.

start	A named list giving the initial values for the parameters over which the weighted sum of square is to be minimized. If <code>start</code> is omitted the routine attempts to find good starting values.
weighted	Logical. Should weighted least squares be used?

### Details

The fitting procedure is based on weighted least squares. More precisely, the fitting criteria is to minimize:

$$\sum_{i,j} \left( \frac{\tilde{\theta}_{i,j} - \hat{\theta}_{i,j}}{s_{i,j}} \right)^2$$

where  $\tilde{\theta}_{i,j}$  is a non parametric estimate of the extremal coefficient related to location  $i$  and  $j$ ,  $\hat{\theta}_{i,j}$  is the fitted extremal coefficient derived from the Schlather's model and  $s_{i,j}$  are the standard errors related to the estimates  $\tilde{\theta}_{i,j}$ .

### Value

An object of class `maxstab`.

### Author(s)

Mathieu Ribatet

### References

Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

### See Also

[fitcovmat](#), [fitmaxstab](#), [fitextcoeff](#)

### Examples

```
n.site <- 50
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulating a max-stable process using RandomFields
##This is the Schlather's approach
data <- rmaxstab(50, locations, cov.mod = "whitmat", sill = 1, range =
30, smooth = 1)

fitcovariance(data, locations, "whitmat")
```

---

fitcovmat

*Estimates the covariance matrix for the Smith's model*


---

### Description

Estimates the covariance matrix for the Smith's model using non-parametric estimates of the pairwise extremal coefficients.

### Usage

```
fitcovmat(data, coord, marge = "emp", iso = FALSE, control = list(),
..., start, weighted = TRUE)
```

### Arguments

data	A matrix representing the data. Each column corresponds to one location.
coord	A matrix that gives the coordinates of each location. Each row corresponds to one location.
marge	Character string specifying how margins are transformed to unit Frechet. Must be one of "emp", "frech" or "mle" - see function <a href="#">fitextcoeff</a> .
iso	Logical. If TRUE, isotropy is supposed. Otherwise (default), anisotropy is allowed.
control	The control arguments to be passed to the <a href="#">optim</a> function.
...	Optional arguments to be passed to the <a href="#">optim</a> function.
start	A named list giving the initial values for the parameters over which the weighted sum of square is to be minimized. If start is omitted the routine attempts to find good starting values.
weighted	Logical. Should weighted least squares be used?

### Details

The fitting procedure is based on weighted least squares. More precisely, the fitting criteria is to minimize:

$$\sum_{i,j} \left( \frac{\tilde{\theta}_{i,j} - \hat{\theta}_{i,j}}{s_{i,j}} \right)^2$$

where  $\tilde{\theta}_{i,j}$  is a non parametric estimate of the extremal coefficient related to location  $i$  and  $j$ ,  $\hat{\theta}_{i,j}$  is the fitted extremal coefficient derived from the Smith's model and  $s_{i,j}$  are the standard errors related to the estimates  $\tilde{\theta}_{i,j}$ .

### Value

An object of class maxstab.

### Author(s)

Mathieu Ribatet

## References

Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

## See Also

[fitcovariance](#), [fitmaxstab](#), [fittextcoeff](#)

## Examples

```
n.site <- 50
n.obs <- 100
locations <- matrix(runif(2*n.site, 0, 40), ncol = 2)
colnames(locations) <- c("lon", "lat")

## Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 200, cov12 =
0, cov22 = 200)

fitcovmat(data, locations)

##Force an isotropic model
fitcovmat(data, locations, iso = TRUE)
```

---

fittextcoeff

*Non parametric estimators of the extremal coefficient function*

---

## Description

Estimates non parametrically the extremal coefficient function.

## Usage

```
fittextcoeff(data, coord, ..., estim = "ST", marge = "emp", prob = 0,
plot = TRUE, loess = TRUE, method = "BFGS", std.err = TRUE, xlab,
ylab, angles = NULL, identify = FALSE)
```

## Arguments

data	A matrix representing the data. Each column corresponds to one location.
coord	A matrix that gives the coordinates of each location. Each row corresponds to one location.
...	Additional options to be passed to the <a href="#">plot</a> function.
estim	Character string specifying the estimator to be used. Must be one of "ST" (Schlather and Tawn) or "Smith".
marge	Character string specifying how margins are transformed to unit Frechet. Must be one of "emp", "mle" or "none" - see Details
prob	The probability related to the threshold. Only useful with the ST estimator.
plot	Logical. If TRUE (default), the extremal coefficient function is plotted
loess	If TRUE (default), a local polynomial curve is plotted - see function <a href="#">loess</a> .

method	The optimizer used when fitting the GEV distribution to data. See function <a href="#">gevml</a> .
std.err	Logical. If TRUE, standard errors are computed. Note that standard errors are not available with the "ST" estimator.
xlab, ylab	The x-axis and y-axis labels. May be missing.
angles	A numeric vector. A partition of the interval $(-\pi, \pi)$ to help detecting anisotropy.
identify	Logical. If TRUE, users can use the <a href="#">identify</a> function to identify pairs of stations on the plot.

### Details

During the estimation procedure, data need to be transformed to unit Frechet margins firsts. This can be done in two different ways ; by using the empirical CDF or the GEV ML estimates.

If `marge = "emp"`, then the data are transformed using the following relation:

$$z_i = -\frac{1}{\log(F(y_i))}$$

where  $y_i$  are the observations available at location  $i$ ,  $F$  is the empirical CDF and  $z_i$  are the observations transformed to unit Frechet scale.

If `marge = "mle"`, then the data are transformed using the MLE of the GEV distribution - see function [gev2frech](#).

Lastly, if data are already supposed to be unit Frechet, then no transformation is performed if one passed the option `marge = "frech"`.

If data are already componentwise maxima, `prob` should be zero. Otherwise, users have to define a threshold  $z$  (large enough) where univariate extreme value arguments are relevant. We define `prob` such that  $\Pr[Z \leq z] = prob$ .

### Value

Plots the extremal coefficient function and returns the points used for the plot. If `loess = TRUE`, the output is a list with argument "ext.coeff" and "loess".

### Author(s)

Mathieu Ribatet

### References

Schlather, M. and Tawn, J. A. (2003) A dependence measure for multivariate and spatial extreme values: Properties and inference. *Biometrika* **90**(1):139–156.

Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

### See Also

[madogram](#)

**Examples**

```
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 10, cov12 =
40, cov22 = 220)

##Plot the extremal coefficient function
op <- par(mfrow=c(1,2))
fitextcoeff(data, locations, estim = "Smith")
fitextcoeff(data, locations, angles = seq(-pi, pi, length = 4), estim = "Smith")
par(op)
```

fitmaxstab

*Fits a max-stable process to data***Description**

This function fits max-stable processes to data using pairwise likelihood. Two max-stable characterisations are available: the Smith and Schlather representations.

**Usage**

```
fitmaxstab(data, coord, cov.mod, loc.form, scale.form,
shape.form, marg.cov = NULL, temp.cov = NULL, temp.form.loc = NULL,
temp.form.scale = NULL, temp.form.shape = NULL, iso = FALSE, ...,
fit.marge = FALSE, warn = TRUE, method = "Nelder", start, control =
list(), weights = NULL, std.err.type = "score", corr = FALSE)
```

**Arguments**

data	A matrix representing the data. Each column corresponds to one location.
coord	A matrix that gives the coordinates of each location. Each row corresponds to one location.
cov.mod	A character string corresponding to the covariance model in the max-stable representation. Must be one of "gauss" for the Smith's model; "whitmat", "cauchy", "powexp", "bessel" or "caugen" for the Whittle-Matern, the Cauchy, the Powered Exponential, the Bessel and the Generalized Cauchy correlation families with the Schlather's model; "brown" for Brown-Resnick processes. The geometric Gaussian and Extremal-t models with a Whittle-Matern correlation function can be fitted by passing respectively "gwhitmat" or "twhitmat". Other correlation function families are considered in a similar way.
loc.form, scale.form, shape.form	R formulas defining the spatial linear model for the GEV parameters. May be missing. See section Details.
marg.cov	Matrix with named columns giving additional covariates for the GEV parameters. If NULL, no extra covariates are used.

<code>temp.cov</code>	Matrix with names columns giving additional *temporal* covariates for the GEV parameters. If <code>NULL</code> , no temporal trend are assume for the GEV parameters — see section Details.
<code>temp.form.loc</code> , <code>temp.form.scale</code> , <code>temp.form.shape</code>	R formulas defining the temporal trends for the GEV parameters. May be missing. See section Details.
<code>iso</code>	Logical. If <code>TRUE</code> an isotropic model is fitted to data. Otherwise (default), anisotropy is allowed. Currently, this is only implemented for the Smith’s model.
<code>...</code>	Several arguments to be passed to the <code>optim</code> , <code>nlm</code> or <code>nlminb</code> functions. See section details.
<code>fit.marge</code>	Logical. If <code>TRUE</code> , the GEV parameters are estimated pointwise or using the formulas given by <code>loc.form</code> , <code>scale.form</code> and <code>shape.form</code> . If <code>FALSE</code> , observations are supposed to be unit Frechet distributed. Note that when formulas are given, <code>fit.marge</code> is automatically set to <code>TRUE</code> .
<code>warn</code>	Logical. If <code>TRUE</code> (default), users are warned if the log-likelihood is infinite at starting values and/or problems arised while computing the standard errors.
<code>method</code>	The method used for the numerical optimisation procedure. Must be one of <code>BFGS</code> , <code>Nelder-Mead</code> , <code>CG</code> , <code>L-BFGS-B</code> , <code>SANN</code> , <code>nlm</code> or <code>nlminb</code> . See <code>optim</code> for details. Please note that passing <code>nlm</code> or <code>nlminb</code> will use the <code>nlm</code> or <code>nlminb</code> functions instead of <code>optim</code> .
<code>start</code>	A named list giving the initial values for the parameters over which the pairwise likelihood is to be minimized. If <code>start</code> is omitted the routine attempts to find good starting values - but might fail.
<code>control</code>	A list giving the control parameters to be passed to the <code>optim</code> function.
<code>weights</code>	A numeric vector specifying the weights in the pairwise likelihood - and so has length the number of pairs. If <code>NULL</code> (default), no weighting scheme is used.
<code>std.err.type</code>	Character string. Must be one of "none", "score", "grad". If "none", standard errors are not computed. Otherwise, standard errors are estimated using the sandwich estimates - see section Details.
<code>corr</code>	Logical. If <code>TRUE</code> (non default), the asymptotic correlation matrix is computed.

## Details

As spatial data often deal with a large number of locations, it is impossible to write analytically the joint distribution. Consequently, the fitting procedure substitutes the "full likelihood" for the pairwise likelihood.

Let define  $L_{i,j}(x_{i,j}, \theta)$  the likelihood for site  $i$  and  $j$ , where  $i = 1, \dots, N - 1$ ,  $j = i + 1, \dots, N$ ,  $N$  is the number of site within the region and  $x_{i,j}$  are the joint observations for site  $i$  and  $j$ . Then the pairwise likelihood  $PL(\theta)$  is defined by:

$$\ell_P = \log PL(\theta) = \sum_{i=1}^{N-1} \sum_{j=i+1}^N \log L_{i,j}(x_{i,j}, \theta)$$

As pairwise likelihood is an approximation of the “full likelihood”, standard errors cannot be computed directly by the inverse of the Fisher information matrix. Instead, a sandwich estimate must be used to account for model misspecification e.g.

$$\hat{\theta} \sim N(\theta, H^{-1} J H^{-1})$$

where  $H$  is the Fisher information matrix (computed from the misspecified model) and  $J$  is the variance of the score function.

$H$  is easily estimated using the observed Hessian matrix given by the `optim` function. Estimation of  $J$  is much more difficult. Currently, we propose two different strategies to estimate  $J$ .

`grad`  $J$  is estimated from the gradient e.g.  $J = \sum_{i=1}^n \left\{ \nabla \ell_P(\hat{\theta}; y_i) \nabla \ell_P(\hat{\theta}; y_i)^T \right\}$ .

`score`  $J$  is estimated directly from the variance of the observed score function.

There are two different kind of covariates : "spatial" and "temporal".

A "spatial" covariate may have different values accross station but does not depend on time. For example the coordinates of the stations are obviously "spatial". These "spatial" covariates should be used with the `marg.cov` and `loc.form`, `scale.form`, `shape.form`.

A "temporal" covariates may have different values accross time but does not depend on space. For example the years where the annual maxima were recorded is "temporal". These "temporal" covariates should be used with the `temp.cov` and `temp.form.loc`, `temp.form.scale`, `temp.form.shape`.

As a consequence note that `marg.cov` must have  $K$  rows ( $K$  being the number of sites) while `temp.cov` must have  $n$  rows ( $n$  being the number of observations).

## Value

This function returns a object of class `maxstab`. Such objects are list with components:

<code>fitted.values</code>	A vector containing the estimated parameters.
<code>std.err</code>	A vector containing the standard errors.
<code>fixed</code>	A vector containing the parameters of the model that have been held fixed.
<code>param</code>	A vector containing all parameters (optimised and fixed).
<code>deviance</code>	The (pairwise) deviance at the maximum pairwise likelihood estimates.
<code>corr</code>	The correlation matrix.
<code>convergence</code> , <code>counts</code> , <code>message</code>	Components taken from the list returned by <code>optim</code> - for the <code>mle</code> method.
<code>data</code>	The data analysed.
<code>model</code>	The max-stable characterisation used.
<code>fit.marge</code>	A logical that specifies if the GEV margins were estimated.
<code>cov.fun</code>	The estimated covariance function - for the Schlather model only.
<code>extCoeff</code>	The estimated extremal coefficient function.
<code>cov.mod</code>	The covariance model for the spatial structure.

## Warning

When using reponse surfaces to model spatially the GEV parameters, the likelihood is pretty rough so that the general purpose optimization routines may fail. It is your responsibility to check if the numerical optimization succeeded or not. I tried, as best as I can, to provide warning messages if the optimizers failed but in some cases, no warning will appear!

## Author(s)

Mathieu Ribatet

## References

- Cox, D. R. and Reid, N. (2004) A note on pseudo-likelihood constructed from marginal densities. *Biometrika* **91**, 729–737.
- Demarta, S. and McNeil, A. (2005) The t copula and Related Copulas *International Statistical Review* **73**, 111-129.
- Gholam-Rezaee, M. (2009) Spatial extreme value: A composite likelihood. PhD Thesis. Ecole Polytechnique Federale de Lausanne.
- Kabluchko, Z., Schlather, M. and de Haan, L. (2009) Stationary max-stable fields associated to negative definite functions *Annals of Probability* **37**:5, 2042–2065.
- Padoan, S. A. (2008) Computational Methods for Complex Problems in Extreme Value Theory. PhD Thesis. University of Padova.
- Padoan, S. A., Ribatet, M. and Sisson, S. A. (2010) Likelihood-based inference for max-stable processes. *Journal of the American Statistical Association (Theory and Methods)* **105**:489, 263-277.
- Schlather, M. (2002) Models for Stationary Max-Stable Random Fields. *Extremes* **5**:1, 33–44.
- Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished.

## Examples

```
## Not run:
##Define the coordinate of each location
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(40, locations, cov.mod = "whitmat", sill = 1, range = 30,
smooth = 0.5)

##Now define the spatial model for the GEV parameters
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1] + locations[,2]^2
param.shape <- rep(0.2, n.site)

##Transform the unit Frechet margins to GEV
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

##Define a model for the GEV margins to be fitted
##shape ~ 1 stands for the GEV shape parameter is constant
##over the region
loc.form <- loc ~ lat
scale.form <- scale ~ lon + I(lat^2)
shape.form <- shape ~ 1

##Fit a max-stable process using the Schlather's model
fitmaxstab(data, locations, "whitmat", loc.form, scale.form,
shape.form)

## Model without any spatial structure for the GEV parameters
## Be careful this could be *REALLY* time consuming
fitmaxstab(data, locations, "whitmat")
```

```

## Fixing the smooth parameter of the Whittle-Matern family
## to 0.5 - e.g. considering exponential family. We suppose the data
## are unit Frechet here.
fitmaxstab(data, locations, "whitmat", smooth = 0.5, fit.marge = FALSE)

## Fitting a penalized smoothing splines for the margins with the
## Smith's model
data <- rmaxstab(40, locations, cov.mod = "gauss", cov11 = 100, cov12 =
                25, cov22 = 220)

## And transform it to ordinary GEV margins with a non-linear
## function
fun <- function(x)
  2 * sin(pi * x / 4) + 10
fun2 <- function(x)
  (fun(x) - 7) / 15

param.loc <- fun(locations[,2])
param.scale <- fun(locations[,2])
param.shape <- fun2(locations[,1])

##Transformation from unit Frechet to common GEV margins
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
                       param.shape[i])

##Defining the knots, penalty, degree for the splines
n.knots <- 5
knots <- quantile(locations[,2], prob = 1:n.knots/(n.knots+1))
knots2 <- quantile(locations[,1], prob = 1:n.knots/(n.knots+1))

##Be careful the choice of the penalty (i.e. the smoothing parameter)
##may strongly affect the result Here we use p-splines for each GEV
##parameter - so it's really CPU demanding but one can use 1 p-spline
##and 2 linear models.
##A simple linear model will be clearly faster...
loc.form <- y ~ rb(lat, knots = knots, degree = 3, penalty = .5)
scale.form <- y ~ rb(lat, knots = knots, degree = 3, penalty = .5)
shape.form <- y ~ rb(lon, knots = knots2, degree = 3, penalty = .5)

fitted <- fitmaxstab(data, locations, "gauss", loc.form, scale.form, shape.form,
                    control = list(ndeps = rep(1e-6, 24), trace = 10),
                    std.err.type = "none", method = "BFGS")

fitted
op <- par(mfrow=c(1,3))
plot(locations[,2], param.loc, col = 2, ylim = c(7, 14),
      ylab = "location parameter", xlab = "latitude")
plot(fun, from = 0, to = 10, add = TRUE, col = 2)
points(locations[,2], predict(fitted)[,"loc"], col = "blue", pch = 5)
new.data <- cbind(lon = seq(0, 10, length = 100), lat = seq(0, 10, length = 100))
lines(new.data[,1], predict(fitted, new.data)[,"loc"], col = "blue")
legend("topleft", c("true values", "predict. values", "true curve", "predict. curve"),
      col = c("red", "blue", "red", "blue"), pch = c(1, 5, NA, NA), inset = 0.05,
      lty = c(0, 0, 1, 1), ncol = 2)

plot(locations[,2], param.scale, col = 2, ylim = c(7, 14),

```

```

      ylab = "scale parameter", xlab = "latitude")
plot(fun, from = 0, to = 10, add = TRUE, col = 2)
points(locations[,2], predict(fitted)[,"scale"], col = "blue", pch = 5)
lines(new.data[,1], predict(fitted, new.data)[,"scale"], col = "blue")
legend("topleft", c("true values", "predict. values", "true curve", "predict. curve"),
      col = c("red", "blue", "red", "blue"), pch = c(1, 5, NA, NA), inset = 0.05,
      lty = c(0, 0, 1, 1), ncol = 2)

plot(locations[,1], param.shape, col = 2,
      ylab = "shape parameter", xlab = "longitude")
plot(fun2, from = 0, to = 10, add = TRUE, col = 2)
points(locations[,1], predict(fitted)[,"shape"], col = "blue", pch = 5)
lines(new.data[,1], predict(fitted, new.data)[,"shape"], col = "blue")
legend("topleft", c("true values", "predict. values", "true curve", "predict. curve"),
      col = c("red", "blue", "red", "blue"), pch = c(1, 5, NA, NA), inset = 0.05,
      lty = c(0, 0, 1, 1), ncol = 2)
par(op)

## End(Not run)

```

---

fitspatgev

*MLE for a spatial GEV model*


---

## Description

This function derives the MLE of a spatial GEV model.

## Usage

```

fitspatgev(data, covariables, loc.form, scale.form, shape.form,
temp.cov = NULL, temp.form.loc = NULL, temp.form.scale = NULL,
temp.form.shape = NULL, ..., start, control = list(maxit = 10000),
method = "Nelder", std.err.type = "score", warn = TRUE, corr = FALSE)

```

## Arguments

<code>data</code>	A matrix representing the data. Each column corresponds to one location.
<code>covariables</code>	Matrix with named columns giving required covariates for the GEV parameter models.
<code>loc.form</code> , <code>scale.form</code> , <code>shape.form</code>	R formulas defining the spatial models for the GEV parameters. See section Details.
<code>temp.cov</code>	Matrix with names columns giving additional *temporal* covariates for the GEV parameters. If <code>NULL</code> , no temporal trend are assume for the GEV parameters — see section Details.
<code>temp.form.loc</code> , <code>temp.form.scale</code> , <code>temp.form.shape</code>	R formulas defining the temporal trends for the GEV parameters. May be missing. See section Details.
<code>start</code>	A named list giving the initial values for the parameters over which the pairwise likelihood is to be minimized. If <code>start</code> is omitted the routine attempts to find good starting values - but might fail.

...	Several arguments to be passed to the <code>optim</code> functions. See section details.
<code>control</code>	The control argument to be passed to the <code>optim</code> function.
<code>method</code>	The method used for the numerical optimisation procedure. Must be one of BFGS, Nelder-Mead, CG, L-BFGS-B or SANN. See <code>optim</code> for details.
<code>std.err.type</code>	Character string. Must be one of "score", "grad" or "none". If none, no standard errors are computed.
<code>warn</code>	Logical. If TRUE (default), users will be warned if the starting values lie in a zero density region.
<code>corr</code>	Logical. If TRUE, the asymptotic correlation matrix is computed.

### Details

A kind of "spatial" GEV model can be defined by using response surfaces for the GEV parameters. For instance, the GEV location parameters are defined through the following equation:

$$\mu = X_{\mu}\beta_{\mu}$$

where  $X_{\mu}$  is the design matrix and  $\beta_{\mu}$  is the vector parameter to be estimated. The GEV scale and shape parameters are defined accordingly to the above equation.

The log-likelihood for the GEV spatial model is consequently defined as follows:

$$\ell(\beta) = \sum_{i=1}^{n.site} \sum_{j=1}^{n.obs} \log f(y_{i,j}; \theta_i)$$

where  $\theta_i$  is the vector of the GEV parameters for the  $i$ -th site.

Most often, there will be some dependence between stations. However, it can be seen from the log-likelihood definition that we supposed that the stations are mutually independent. Consequently, to get reliable standard error estimates, these standard errors are estimated with their sandwich estimates.

There are two different kind of covariates : "spatial" and "temporal".

A "spatial" covariate may have different values accross station but does not depend on time. For example the coordinates of the stations are obviously "spatial". These "spatial" covariates should be used with the `marg.cov` and `loc.form`, `scale.form`, `shape.form`.

A "temporal" covariates may have different values accross time but does not depend on space. For example the years where the annual maxima were recorded is "temporal". These "temporal" covariates should be used with the `temp.cov` and `temp.form.loc`, `temp.form.scale`, `temp.form.shape`.

As a consequence note that `marg.cov` must have  $K$  rows ( $K$  being the number of sites) while `temp.cov` must have  $n$  rows ( $n$  being the number of observations).

### Value

An object of class `spatgev`. Namely, this is a list with the following arguments:

<code>fitted.values</code>	The parameter estimates.
<code>param</code>	All the parameters e.g. parameter estimates and fixed parameters.
<code>std.err</code>	The standard errors.

var.cov            The asymptotic MLE variance covariance matrix.  
 counts,message,convergence            Some information about the optimization procedure.  
 logLik,deviance            The log-likelihood and deviance values.  
 loc.form, scale.form, shape.form            The formulas defining the spatial models for the GEV parameters.  
 covariables            The covariables used for the spatial models.  
 ihessian            The inverse of the Hessian matrix of the negative log-likelihood.  
 jacobian            The variance covariance matrix of the score.

**Author(s)**

Mathieu Ribatet

**Examples**

```
## 1- Simulate a max-stable random field
n.site <- 35
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")
data <- rmaxstab(50, locations, cov.mod = "whitmat", sill = 1, range =
  3, smooth = 0.5)

## 2- Transformation to non unit Frechet margins
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1]
param.shape <- rep(0.2, n.site)
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
    param.shape[i])

## 3- Fit a 'spatial GEV' model to data with the following models for
## the GEV parameters
form.loc <- loc ~ lat
form.scale <- scale ~ lon
form.shape <- shape ~ 1

fitspatgev(data, locations, form.loc, form.scale, form.shape)
```

---

fmadogram

*Computes the F-madogram*

---

**Description**

Computes the F-madogram for max-stable processes.

**Usage**

```
fmadogram(data, coord, fitted, n.bins, which = c("mado", "ext"), xlab,
  ylab, col = c(1, 2), angles = NULL, marge = "emp", add = FALSE, xlim =
  c(0, max(dist)), ...)
```

**Arguments**

<code>data</code>	A matrix representing the data. Each column corresponds to one location.
<code>coord</code>	A matrix that gives the coordinates of each location. Each row corresponds to one location.
<code>fitted</code>	An object of class <code>maxstab</code> - usually the output of the <code>fitmaxstab</code> function. May be missing.
<code>n.bins</code>	The number of bins to be used. If missing, pairwise F-madogram estimates will be computed.
<code>which</code>	A character vector of maximum size 2. It specifies if the madogram and/or the extremal coefficient functions have to be plotted.
<code>xlab, ylab</code>	The x-axis and y-axis labels. May be missing. Note that <code>ylab</code> must have the same length as <code>which</code> .
<code>col</code>	The colors used for the points and optionally the fitted curve.
<code>angles</code>	A numeric vector. A partition of the interval $(-\pi, \pi)$ to help detecting anisotropy.
<code>marge</code>	Character string. If 'emp', the probabilities of non exceedances are estimated using the empirical CDF. If 'mle' (default), maximum likelihood estimates are used.
<code>add</code>	Logical. If <code>TRUE</code> , the plot is added to the current figure; otherwise (default) a new plot is computed.
<code>xlim</code>	A numeric vector of length 2 specifying the x coordinate range.
<code>...</code>	Additional options to be passed to the <code>plot</code> function.

**Details**

Let  $Z(x)$  be a stationary process. The F-madogram is defined as follows:

$$\nu(h) = \frac{1}{2} \text{E} [|F(Z(x+h)) - F(Z(x))|]$$

The extremal coefficient  $\theta(h)$  satisfies:

$$\theta(h) = \frac{1 + 2\nu(h)}{1 - 2\nu(h)}$$

**Value**

A graphic and (invisibly) a matrix with the lag distances, the F-madogram and extremal coefficient estimates.

**Author(s)**

Mathieu Ribatet

**References**

Cooley, D., Naveau, P. and Poncet, P. (2006) Variograms for spatial max-stable random fields. *Dependence in Probability and Statistics*, 373–390.

**See Also**

[madogram](#), [lmadogram](#)

**Examples**

```

n.site <- 15
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(40, locations, cov.mod = "whitmat", sill = 1, range = 1,
smooth = 2)

##Compute the F-madogram
fmadogram(data, locations)

##Compare the F-madogram with a fitted max-stable process
fitted <- fitmaxstab(data, locations, "whitmat", sill = 1)
fmadogram(fitted = fitted, which = "ext")

```

gcv

*Estimates the penalty coefficient from the generalized cross-validation***Description**

Estimates the penalty coefficient from the generalized cross-validation criterion.

**Usage**

```
gcv(y, x, knots, degree, plot = TRUE, n.points = 150, ...)
```

**Arguments**

y	The response vector.
x	A vector/matrix giving the values of the predictor variable(s). If x is a matrix, each row corresponds to one observation.
knots	A vector giving the coordinates of the knots.
degree	The degree of the penalized smoothing spline.
plot	Logical. If TRUE (default), the evolution of the CV score as the penalty increases is plotted.
n.points	A numeric giving the number of CV computations needed to produce the plot.
...	Options to be passed to the <code>nlm</code> function.

**Details**

For every linear smoother e.g.  $\hat{y} = S_\lambda y$ , the cross-validation criterion consists in minimizing the following quantity:

$$GCV(\lambda) = \frac{n \|y - \hat{y}\|^2}{(n - \text{tr}(S_\lambda))^2}$$

where  $\lambda$  is the penalty coefficient,  $n$  the number of observations and  $\text{tr}(S_\lambda)$  is the trace of the matrix  $S_\lambda$ .

**Value**

A list with components 'penalty', 'gcv' and 'nlm.code' which give the location of the minimum, the value of the cross-validation criterion at that point and the code returned by the `link{nlm}` function - useful to assess for convergence issues.

**Author(s)**

Mathieu Ribatet

**References**

Ruppert, D. Wand, M.P. and Carrol, R.J. (2003) *Semiparametric Regression* Cambridge Series in Statistical and Probabilistic Mathematics.

**See Also**

[cv](#)

**Examples**

```
n <- 200
x <- runif(n)
fun <- function(x) sin(3 * pi * x)
y <- fun(x) + rnorm(n, 0, sqrt(0.4))
knots <- quantile(x, prob = 1:(n/4) / (n/4 + 1))
gcv(y, x, knots = knots, degree = 3)
```

---

Generalized Extreme Value Distribution

*The Generalized Extreme Value Distribution*

---

**Description**

Density, distribution function, quantile function and random generation for the GP distribution with location equal to 'loc', scale equal to 'scale' and shape equal to 'shape'.

**Usage**

```
rgev(n, loc = 0, scale = 1, shape = 0)
pgev(q, loc = 0, scale = 1, shape = 0, lower.tail = TRUE)
qgev(p, loc = 0, scale = 1, shape = 0, lower.tail = TRUE)
dgev(x, loc = 0, scale = 1, shape = 0, log = FALSE)
```

**Arguments**

<code>x</code> , <code>q</code>	vector of quantiles.
<code>p</code>	vector of probabilities.
<code>n</code>	number of observations.
<code>loc</code>	vector of the location parameters.
<code>scale</code>	vector of the scale parameters.

shape	a numeric of the shape parameter.
lower.tail	logical; if TRUE (default), probabilities are $\Pr[X \leq x]$ , otherwise, $\Pr[X > x]$ .
log	logical; if TRUE, probabilities p are given as $\log(p)$ .

**Value**

If 'loc', 'scale' and 'shape' are not specified they assume the default values of '0', '1' and '0', respectively.

The GEV distribution function for  $\text{loc} = u$ ,  $\text{scale} = \sigma$  and  $\text{shape} = \xi$  is

$$G(x) = \exp \left[ - \left\{ 1 + \xi \frac{x - u}{\sigma} \right\}^{-1/\xi} \right]$$

for  $1 + \xi(x - u)/\sigma > 0$  and  $x > u$ , where  $\sigma > 0$ . If  $\xi = 0$ , the distribution is defined by continuity corresponding to the Gumbel distribution.

**Examples**

```
dgev(0.1)
rgev(100, 1, 2, 0.2)
qgev(seq(0.1, 0.9, 0.1), 1, 0.5, -0.2)
pgev(12.6, 2, 0.5, 0.1)
```

---

Generalized Pareto Distribution

*The Generalized Pareto Distribution*

---

**Description**

Density, distribution function, quantile function and random generation for the GP distribution with location equal to 'loc', scale equal to 'scale' and shape equal to 'shape'.

**Usage**

```
rgpd(n, loc = 0, scale = 1, shape = 0)
pgpd(q, loc = 0, scale = 1, shape = 0, lower.tail = TRUE, lambda = 0)
qqpd(p, loc = 0, scale = 1, shape = 0, lower.tail = TRUE, lambda = 0)
dgp(x, loc = 0, scale = 1, shape = 0, log = FALSE)
```

**Arguments**

x, q	vector of quantiles.
p	vector of probabilities.
n	number of observations.
loc	vector of the location parameters.
scale	vector of the scale parameters.
shape	a numeric of the shape parameter.
lower.tail	logical; if TRUE (default), probabilities are $\Pr[X \leq x]$ , otherwise, $\Pr[X > x]$ .
log	logical; if TRUE, probabilities p are given as $\log(p)$ .
lambda	a single probability - see the "value" section.

**Value**

If 'loc', 'scale' and 'shape' are not specified they assume the default values of '0', '1' and '0', respectively.

The GP distribution function for  $\text{loc} = u$ ,  $\text{scale} = \sigma$  and  $\text{shape} = \xi$  is

$$G(x) = 1 - \left[ 1 + \frac{\xi(x-u)}{\sigma} \right]^{-1/\xi}$$

for  $1 + \xi(x-u)/\sigma > 0$  and  $x > u$ , where  $\sigma > 0$ . If  $\xi = 0$ , the distribution is defined by continuity corresponding to the exponential distribution.

By definition, the GP distribution models exceedances above a threshold. In particular, the  $G$  function is a suited candidate to model

$$\Pr[X \geq x | X > u] = 1 - G(x)$$

for  $u$  large enough.

However, it may be useful to model the "non conditional" quantiles, that is the ones related to  $\Pr[X \leq x]$ . Using the conditional probability definition, one have :

$$\Pr[X \geq x] = (1 - \lambda) \left( 1 + \xi \frac{x-u}{\sigma} \right)^{-1/\xi}$$

where  $\lambda = \Pr[X \leq u]$ .

When  $\lambda = 0$ , the "conditional" distribution is equivalent to the "non conditional" distribution.

**Examples**

```
dgpd(0.1)
rgpd(100, 1, 2, 0.2)
qgpd(seq(0.1, 0.9, 0.1), 1, 0.5, -0.2)
pgpd(12.6, 2, 0.5, 0.1)
##for non conditional quantiles
qgpd(seq(0.9, 0.99, 0.01), 1, 0.5, -0.2, lambda = 0.9)
pgpd(2.6, 2, 2.5, 0.25, lambda = 0.5)
```

---

 gev2frech

*Transforms GEV data to unit Frechet ones and vice versa*


---

**Description**

Transforms GEV data to unit Frechet ones and vice versa

**Usage**

```
gev2frech(x, loc, scale, shape, emp = FALSE)
frech2gev(x, loc, scale, shape)
```

**Arguments**

<code>x</code>	The data to be transformed to unit Frechet or ordinary GEV margins
<code>loc, scale, shape</code>	The location, scale and shape parameters of the GEV.
<code>emp</code>	Logical. If TRUE, data are transformed to unit Frechet margins using the empirical CDF.

**Details**

If  $Y$  is a random variable with a GEV distribution with location  $\mu$ , scale  $\sigma$  and shape  $\xi$ . Then,

$$Z = \left[ 1 + \xi \frac{Y - \mu}{\sigma} \right]_+^{1/\xi}$$

is unit Frechet distributed - where  $x_+ = \max(0, x)$ .

If  $Z$  is a unit Frechet random variable. Then,

$$Y = \mu + \sigma \frac{Z_+^\xi - 1}{\xi}$$

is unit GEV distributed with location, scale and shape parameters equal to  $\mu$ ,  $\sigma$  and  $\xi$  respectively.

**Value**

Returns a numeric vector with the same length of `x`

**Author(s)**

Mathieu Ribatet

**Examples**

```
x <- c(2.2975896, 1.6448808, 1.3323833, -0.4464904, 2.2737603,
      -0.2581876, 9.5184398, -0.5899699, 0.4974283, -0.8152157)
y <- gev2frech(x, 1, 2, .2)
y
frech2gev(y, 1, 2, .2)
```

---

kriging

*Simple kriging interpolation*


---

**Description**

This function interpolates a zero mean Gaussian random field using the simple kriging predictor.

**Usage**

```
kriging(data, data.coord, krig.coord, cov.mod = "whitmat", sill, range,
smooth, smooth2 = NULL, grid = FALSE, only.weights = FALSE)
```

**Arguments**

<code>data</code>	A numeric vector or matrix. If <code>data</code> is a matrix then the simple kriging predictor is given for each realisation, i.e., each row of <code>data</code> .
<code>data.coord</code>	A numeric vector or matrix specifying the coordinates of the observed data. If <code>data.coord</code> is a matrix, each row must corresponds to one location.
<code>krig.coord</code>	A numeric vector or matrix specifying the coordinates where the kriging predictor has to be computed. If <code>krig.coord</code> is a matrix, each row must correspond to one location.
<code>cov.mod</code>	A character string specifying the covariance function family. Must be one of "whitmat", "powexp", "cauchy", "bessel" or "caugen" for the Whittle-Matern, the powered exponential, the Cauchy, the Bessel or the generalized Cauchy covariance families.
<code>sill, range, smooth, smooth2</code>	Numerics specifying the sill, range, smooth and, if any, the second smooth parameters of the covariance function.
<code>grid</code>	Logical. Does <code>krig.coord</code> specifies a grid?
<code>only.weights</code>	Logical. Should only the kriging weights be computed? If <code>FALSE</code> , the kriging predictor isn't computed.

**Value**

A list with components

<code>coord</code>	The coordinates where the kriging predictor has been computed;
<code>krig.est</code>	The kriging predictor estimates;
<code>grid</code>	Does <code>coord</code> define a grid?;
<code>weights</code>	A matrix giving the kriging weights: each column corresponds to one prediction location.

**Author(s)**

Mathieu Ribatet

**References**

Chiles, J.-P. and Delfiner, P. (1999) *Geostatistics, Modeling Spatial Uncertainty* Wiley Series in Probability and Statistics.

**See Also**

[condrgp](#), [rgp](#), [covariance](#).

**Examples**

```
## Kriging from a single realisation
n.site <- 50
n.pred <- 512

x.obs <- runif(n.site, -100, 100)
x.pred <- seq(-100, 100, length = n.pred)

data <- rgp(1, x.obs, "whitmat", sill = 1, range = 10, smooth = 0.75)
```

```

krig <- kriging(data, x.obs, x.pred, "whitmat", sill = 1, range = 10,
smooth = 0.75)

plot(krig$coord, krig$krig.est, type = "l", xlab = "x", ylab =
expression(hat(Y)(x)))
points(x.obs, data, col = 2, pch = 21, bg = 2)

## Kriging from several realisations
n.real <- 3
data <- rgp(n.real, x.obs, "whitmat", sill = 1, range = 10, smooth = 0.75)

krig <- kriging(data, x.obs, x.pred, "whitmat", sill = 1, range = 10,
smooth = 0.75)

matplot(krig$coord, t(krig$krig.est), type = "l", xlab = "x", ylab =
expression(hat(Y)(x)), lty = 1)
matpoints(x.obs, t(data), pch = 21, col = 1:n.real, bg = 1:n.real)
title("Three kriging predictors in one shot")

## Two dimensional kriging on a grid
x.obs <- matrix(runif(2 * n.site, -100, 100), ncol = 2)
x <- y <- seq(-100, 100, length = 100)
x.pred <- cbind(x, y)

data <- rgp(1, x.obs, "whitmat", sill = 1, range = 10, smooth = 0.75)

krig <- kriging(data, x.obs, x.pred, "whitmat", sill = 1, range = 10,
smooth = 0.75, grid = TRUE)

z.lim <- range(c(data, krig$krig.est))
breaks <- seq(z.lim[1], z.lim[2], length = 65)
col <- heat.colors(64)
idx <- as.numeric(cut(data, breaks))

image(x, y, krig$krig.est, col = col, breaks = breaks)
points(x.obs, bg = col[idx], pch = 21)
## Note how the background colors of the above points matches the ones
## returned by the image function

```

---

latent

*Bayesian hierarchical models for spatial extremes*


---

### Description

This function generates a Markov chain from a Bayesian hierarchical model for block maxima assuming conditional independence.

### Usage

```

latent(data, coord, cov.mod = "powexp", loc.form, scale.form,
shape.form, marg.cov = NULL, hyper, prop, start, n = 5000, thin = 1,
burn.in = 0)

```

**Arguments**

<code>data</code>	A matrix representing the data. Each column corresponds to one location.
<code>coord</code>	A matrix that gives the coordinates of each location. Each row corresponds to one location.
<code>cov.mod</code>	A character string corresponding to the covariance model for the Gaussian latent processes. Must be one of "gauss" for the Smith's model; "whitmat", "cauchy", "powexp" or "bessel" or for the Whittle-Matern, the Cauchy, the Powered Exponential and the Bessel correlation families.
<code>loc.form, scale.form, shape.form</code>	R formulas defining the spatial linear model for the mean of the latent processes.
<code>marg.cov</code>	Matrix with named columns giving additional covariates for the latent processes means. If <code>NULL</code> , no extra covariates are used.
<code>hyper</code>	A named list specifying the hyper-parameters — see Details.
<code>prop</code>	A named list specifying the jump sizes when a Metropolis–Hastings move is needed — see Details.
<code>start</code>	A named list specifying the starting values — see Details.
<code>n</code>	The effective length of the simulated Markov chain i.e., once the burnin period has been discarded and after thinning.
<code>thin</code>	An integer specifying the thinning length. The default is 1, i.e., no thinning.
<code>burn.in</code>	An integer specifying the burnin period. The default is 0, i.e., no burnin.

**Details**

This function generates a Markov chain from the following model. For each  $x \in R^d$ , suppose that  $Y(x)$  is GEV distributed whose parameters  $\{\mu(x), \sigma(x), \xi(x)\}$  vary smoothly for  $x \in R^d$  according to a stochastic process  $S(x)$ . We assume that the processes for each GEV parameters are mutually independent Gaussian processes. For instance, we take for the location parameter  $\mu(x)$

$$\mu(x) = f_{\mu(x)}(x; \beta_{\mu}) + S_{\mu}(x; \alpha_{\mu}, \lambda_{\mu}, \kappa_{\mu})$$

where  $f_{\mu}$  is a deterministic function depending on regression parameters  $\beta_{\mu}$ , and  $S_{\mu}$  is a zero mean, stationary Gaussian process with a prescribed covariance function with sill  $\alpha_{\mu}$ , range  $\lambda_{\mu}$  and shape parameters  $\kappa_{\mu}$ . Similar formulations for the scale  $\sigma(x)$  and the shape  $\xi(x)$  parameters are used. Then conditional on the values of the three Gaussian processes at the sites  $(x_1, \dots, x_K)$ , the maxima are assumed to follow GEV distributions

$$Y_i(x_j) \mid \{\mu(x_j), \sigma(x_j), \xi(x_j)\} \sim \text{GEV}\{\mu(x_j), \sigma(x_j), \xi(x_j)\},$$

independently for each location  $(x_1, \dots, x_K)$ .

A joint prior density must be defined for the sills, ranges, shapes parameters of the covariance functions as well as for the regression parameters  $\beta_{\mu}$ ,  $\beta_{\sigma}$  and  $\beta_{\xi}$ . Conjugate priors are used whenever possible, taking independent inverse Gamma and multivariate normal distributions for the sills and the regression parameters. No conjugate prior exist for  $\lambda$  and  $\kappa$ , for wich a Gamma distribution is assumed.

Consequently `hyper` is a named list with named components

**sills** A list with three components named 'loc', 'scale' and 'shape' each of these is a 2-length vector specifying the shape and the scale of the inverse Gamma prior distribution for the sill parameter of the covariance functions;

**ranges** A list with three components named 'loc', 'scale' and 'shape' each of these is a 2-length vector specifying the shape and the scale of the Gamma prior distribution for the range parameter of the covariance functions.

**smooths** A list with three components named 'loc', 'scale' and 'shape' each of these is a 2-length vector specifying the shape and the scale of the Gamma prior distribution for the shape parameter of the covariance functions;

**betaMean** A list with three components named 'loc', 'scale' and 'shape' each of these is a vector specifying the mean vector of the multivariate normal prior distribution for the regression parameters;

**betaIcov** A list with three components named 'loc', 'scale' and 'shape' each of these is a matrix specifying the inverse of the covariance matrix of the multivariate normal prior distribution for the regression parameters.

As no conjugate prior exists for the GEV parameters and the range and shape parameters of the covariance functions, Metropolis–Hastings steps are needed. The proposals  $\theta_{prop}$  are drawn from a proposal density  $q(\cdot | \theta_{cur}, s)$  where  $\theta_{cur}$  is the current state of the parameter and  $s$  is a parameter of the proposal density to be defined. These proposals are driven by `PROP` which is a list with three named components

**gev** A vector of length 3 specifying the jump sizes for the location, scale and shape GEV parameters —  $\theta_{prop} = \theta_{cur} + s(U - 0.5)$ ,  $U \sim U(0, 1)$ ;

**ranges** A vector of length 3 specifying the jump sizes for the range parameters of the covariance functions —  $q(\cdot | \theta_{cur}, s)$  is the log-normal density with mean  $\theta_{cur}$  and standard deviation  $s$  both on the log-scale;

**smooths** A vector of length 3 specifying the jump sizes for the shape parameters of the covariance functions —  $q(\cdot | \theta_{cur}, s)$  is the log-normal density with mean  $\theta_{cur}$  and standard deviation  $s$  both on the log-scale.

If one want to held fixed a parameter this can be done by setting a null jump size then the parameter will be held fixed to its starting value.

Finally `start` must be a named list with 4 named components

**sills** A vector of length 3 specifying the starting values for the sill of the covariance functions;

**ranges** A vector of length 3 specifying the starting values for the range of the covariance functions;

**smooths** A vector of length 3 specifying the starting values for the shape of the covariance functions;

**beta** A named list with 3 components 'loc', 'scale' and 'shape' each of these is a numeric vector specifying the starting values for the regression coefficients.

## Value

A list

## Warning

This function can be time consuming and makes an intensive use of BLAS routines so it is (much!) faster if you have an optimized BLAS.

The starting values will never be stored in the generated Markov chain even when `burn.in=0`.

## Note

If you want to analyze the convergence and mixing properties of the Markov chain, it is recommended to use the library `coda`.

**Author(s)**

Mathieu Ribatet

**References**

Banerjee, S., Carlin, B. P., and Gelfand, A. E. (2004). Hierarchical Modeling and Analysis for Spatial Data. Chapman & Hall/CRC, New York.

Casson, E. and Coles, S. (1999) Spatial regression models for extremes. *Extremes* **1**,449–468.

Cooley, D., Nychka, D. and Naveau, P. (2007) Bayesian spatial modelling of extreme precipitation return levels *Journal of the American Statistical Association* **102**:479, 824–840.

Davison, A.C., Padoan, S.A. and Ribatet, M. Statistical Modelling of Spatial Extremes. Submitted.

**Examples**

```
## Generate realizations from the model
n.site <- 30
n.obs <- 50
coord <- cbind(lon = runif(n.site, -10, 10), lat = runif(n.site, -10 , 10))

gp.loc <- rgp(1, coord, "powexp", sill = 4, range = 20, smooth = 1)
gp.scale <- rgp(1, coord, "powexp", sill = 0.4, range = 5, smooth = 1)
gp.shape <- rgp(1, coord, "powexp", sill = 0.01, range = 10, smooth = 1)

locs <- 26 + 0.5 * coord[,"lon"] + gp.loc
scales <- 10 + 0.2 * coord[,"lat"] + gp.scale
shapes <- 0.15 + gp.shape

data <- matrix(NA, n.obs, n.site)
for (i in 1:n.site)
  data[,i] <- rgev(n.obs, locs[i], scales[i], shapes[i])

loc.form <- y ~ lon
scale.form <- y ~ lat
shape.form <- y ~ 1

hyper <- list()
hyper$sills <- list(loc = c(1,8), scale = c(1,1), shape = c(1,0.02))
hyper$ranges <- list(loc = c(2,20), scale = c(1,5), shape = c(1, 10))
hyper$smooths <- list(loc = c(1,1/3), scale = c(1,1/3), shape = c(1, 1/3))
hyper$betaMeans <- list(loc = rep(0, 2), scale = c(9, 0), shape = 0)
hyper$betaIcov <- list(loc = solve(diag(c(400, 100))),
                      scale = solve(diag(c(400, 100))),
                      shape = solve(diag(c(10), 1, 1)))

## We will use an exponential covariance function so the jump sizes for
## the shape parameter of the covariance function are null.
prop <- list(gev = c(2.5, 1.5, 0.2), ranges = c(0.7, 0.75, 0.9), smooths = c(0,0,0))
start <- list(sills = c(4, .36, 0.009), ranges = c(24, 17, 16), smooths
            = c(1, 1, 1), beta = list(loc = c(26, 0.5), scale = c(10, 0.2),
            shape = c(0.15)))

mc <- latent(data, coord, loc.form = loc.form, scale.form = scale.form,
            shape.form = shape.form, hyper = hyper, prop = prop, start = start,
            n = 500)

mc
```

---

lmadogram	<i>Computes the lambda-madogram</i>
-----------	-------------------------------------

---

### Description

Computes the lambda-madogram for max-stable processes.

### Usage

```
lmadogram(data, coord, n.bins, xlab, ylab, zlab, n.lambda = 11, marge =
"emp", col = terrain.colors(50, alpha = 0.5), theta = 90, phi = 20,
border = NA, ...)
```

### Arguments

data	A matrix representing the data. Each column corresponds to one location.
coord	A matrix that gives the coordinates of each location. Each row corresponds to one location.
n.bins	The number of bins to be used. If missing, pairwise lambda-madogram estimates will be computed.
xlab, ylab, zlab	The x-axis, y-axis and z-axis labels. May be missing.
n.lambda	Integer giving the number of lambda values.
marge	Character string. If 'emp', probabilities of non exceedances are estimated using the empirical CDF. If 'mle' (default), maximum likelihood estimates are used.
col	The colors used to emphasize the gradient of the lambda-madogram.
theta, phi, border	Options to be passed to the <code>persp</code> function.
...	Additional options to be passed to the <code>persp</code> function.

### Details

Let  $Z(x)$  be a stationary process. The  $\lambda$ -madogram is defined as follows:

$$\nu_\lambda(h) = \frac{1}{2} \mathbb{E} [ |F^\lambda(Z(x+h)) - F^{1-\lambda}(Z(x))| ]$$

### Value

A graphic and (invisibly) a matrix with the lag distances, the  $\lambda$ -madogram estimate.

### Author(s)

Mathieu Ribatet

### References

Naveau, P., Guillou, A., Cooley, D. and Diebolt, J. (2009) Modelling Pairwise Dependence of Maxima in Space. To appear in *Biometrika*.

**See Also**

[madogram](#), [fmadogram](#)

**Examples**

```
n.site <- 50
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(40, locations, cov.mod = "whitmat", sill = 1, range = 1,
smooth = 2)

##Compute the lambda-madogram
lmadogram(data, locations, n.bins = 80)
```

---

logLik

*Extracts Log-Likelihood*

---

**Description**

Extract the pairwise log-likelihood for objects of class “maxstab”

**Usage**

```
## S3 method for class 'maxstab'
logLik(object, ...)
```

**Arguments**

object	An object of class “maxstab”. Most often this will be the output of the <a href="#">fitmaxstab</a> function.
...	Other arguments to be passed to the <a href="#">logLik</a> function.

**Value**

Standard [logLik](#) object (see [logLik](#)) except that this is the pairwise log-likelihood!

**Author(s)**

Mathieu Ribatet

**See Also**

[logLik](#)

## Examples

```
##Define the coordinates of each location
n.site <- 30
locations <- matrix(5 + runif(2*n.site, 0, 10), ncol = 2)

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(30, locations, cov.mod = "whitmat", sill = 1, range = 3,
smooth = 0.5)
fit <- fitmaxstab(data, locations, "whitmat")
logLik(fit)
```

---

lsmastab	<i>Estimates the spatial dependence parameter of a max-stable process by</i>
----------	--

---

## Description

Estimates the spatial dependence parameter of a max-stable process by minimizing least squares.

## Usage

```
lsmastab(data, coord, cov.mod = "gauss", marge = "emp", control =
list(), iso = FALSE, ..., weighted = TRUE)
```

## Arguments

data	A matrix representing the data. Each column corresponds to one location.
coord	A matrix that gives the coordinates of each location. Each row corresponds to one location.
cov.mod	Character string specifying the max-stable process considered. Must be one of "gauss" (Smith's model), "whitmat", "cauchy", "powexp", "bessel", "caugen" for the Schlather model with the corresponding correlation function.
marge	Character string specifying how margins are transformed to unit Frechet. Must be one of "emp", "frech" or "mle" - see function <a href="#">fitextcoeff</a> .
control	The control arguments to be passed to the <a href="#">optim</a> function.
iso	Logical. If TRUE, isotropy is supposed. Otherwise (default), anisotropy is allowed. Currently this is only useful for the Smith model.
...	Optional arguments.
weighted	Logical. Should weighted least squares be used? See Details.

## Details

The fitting procedure is based on weighted least squares. More precisely, the fitting criteria is to minimize:

$$\sum_{i,j} \left( \frac{\tilde{\theta}_{i,j} - \hat{\theta}_{i,j}}{s_{i,j}} \right)^2$$

where  $\tilde{\theta}_{i,j}$  is a non parametric estimate of the extremal coefficient related to location  $i$  and  $j$ ,  $\hat{\theta}_{i,j}$  is the fitted extremal coefficient derived from the maxstable model considered and  $s_{i,j}$  are the standard errors related to the estimates  $\tilde{\theta}_{i,j}$ .

**Value**

An object of class `maxstab`.

**Author(s)**

Mathieu Ribatet

**References**

Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

**See Also**

[fitcovariance](#), [fitmaxstab](#), [fitextcoeff](#)

**Examples**

```
n.site <- 50
n.obs <- 100
locations <- matrix(runif(2*n.site, 0, 40), ncol = 2)
colnames(locations) <- c("lon", "lat")

## Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 200, cov12 =
0, cov22 = 200)

lsmxstab(data, locations, "gauss")

##Force an isotropic model and do not use weights
lsmxstab(data, locations, "gauss", iso = TRUE, weighted = FALSE)
```

---

madogram

*Computes madograms*

---

**Description**

Computes the madogram for max-stable processes.

**Usage**

```
madogram(data, coord, fitted, n.bins, gev.param = c(0, 1, 0), which =
c("mado", "ext"), xlab, ylab, col = c(1, 2), angles = NULL, marge =
"emp", add = FALSE, xlim = c(0, max(dist)), ...)
```

**Arguments**

<code>data</code>	A matrix representing the data. Each column corresponds to one location.
<code>coord</code>	A matrix that gives the coordinates of each location. Each row corresponds to one location.
<code>fitted</code>	An object of class <code>maxstab</code> - usually the output of the <a href="#">fitmaxstab</a> function. May be missing.

n.bins	The number of bins to be used. If missing, pairwise madogram estimates will be computed.
gev.param	Numeric vector of length 3 specifying the location, scale and shape parameters for the GEV.
which	A character vector of maximum size 2. It specifies if the madogram and/or the extremal coefficient functions have to be plotted.
xlab, ylab	The x-axis and y-axis labels. May be missing. Note that ylab must have the same length as which.
col	The colors used for the points and optionally for the fitted curve.
angles	A numeric vector. A partition of the interval $(0, \pi)$ to help detecting anisotropy.
marge	Character string. If 'emp', the observations are first transformed to the unit Fréchet scale by using the empirical CDF. If 'mle' (default), maximum likelihood estimates are used.
add	Logical. If TRUE, the plot is added to the current figure; otherwise (default) a new plot is computed.
xlim	A numeric vector of length 2 specifying the x coordinate range.
...	Additional options to be passed to the plot function.

### Details

Let  $Z(x)$  be a stationary process. The madogram is defined as follows:

$$\nu(h) = \frac{1}{2} \mathbb{E}[|Z(x+h) - Z(x)|]$$

If now  $Z(x)$  is a stationary max-stable random field with GEV marginals. Provided the GEV shape parameter  $\xi$  is such that  $\xi < 1$ . The extremal coefficient  $\theta(h)$  satisfies:

$$\theta(h) = \begin{cases} u_\beta \left( \mu + \frac{\nu(h)}{\Gamma(1-\xi)} \right), & \xi \neq 0 \\ \exp \left( \frac{\nu(h)}{\sigma} \right), & \xi = 0 \end{cases}$$

where  $\Gamma(\cdot)$  is the gamma function and  $u_\beta$  is defined as follows:

$$u_\beta(u) = \left( 1 + \xi \frac{u - \mu}{\sigma} \right)_+^{1/\xi}$$

and  $\beta = (\mu, \sigma, \xi)$  i.e the vector of the GEV parameters.

### Value

A graphic and (invisibly) a matrix with the lag distances, the madogram and extremal coefficient estimates.

### Author(s)

Mathieu Ribatet

### References

Cooley, D., Naveau, P. and Poncet, P. (2006) Variograms for spatial max-stable random fields. *Dependence in Probability and Statistics*, 373–390.

**See Also**

[fmadogram](#), [lmadogram](#)

**Examples**

```
n.site <- 15
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(40, locations, cov.mod = "whitmat", sill = 1, range = 1,
smooth = 2)

##Compute the madogram
madogram(data, locations)

##Compare the madogram with a fitted max-stable model
fitted <- fitmaxstab(data, locations, "whitmat", sill = 1)
madogram(fitted = fitted, which = "ext")
```

---

map

*Produces a 2D map from a fitted max-stable process*


---

**Description**

Produces a 2D map from a fitted max-stable process.

**Usage**

```
map(fitted, x, y, covariates = NULL, param = "quant", ret.per = 100, col
= terrain.colors(64), plot.contour = TRUE, ...)
```

**Arguments**

fitted	An object of class <code>maxstab</code> . Most often, it will be the output of the function <code>fitmaxstab</code> .
x, y	Numeric vector that gives the coordinates of the grid.
covariates	An array specifying the covariates at each grid point defined by <code>x</code> and <code>y</code> . If <code>NULL</code> , no covariate is needed. See the example to see how to build it.
param	A character string. Must be one of "loc", "scale", "shape" or "quant" for a map of the location, scale, shape parameters or for a map of a specified quantile.
ret.per	A numeric giving the return period for which the quantile map is plotted. It is only required if <code>param = "quant"</code> .
col	A list of colors such as that generated by 'rainbow', 'heat.colors', 'topo.colors', 'terrain.colors' or similar functions.
plot.contour	Logical. If <code>TRUE</code> (default), contour lines are added to the plot.
...	Several arguments to be passed to the <code>link{image}</code> function.

**Value**

A plot. Additionally, a list with the details for plotting the map is returned invisibly.

**Author(s)**

Mathieu Ribatet

**See Also**

[condmap](#), [filled.contour](#), [heatmap](#), [heat.colors](#), [topo.colors](#), [terrain.colors](#), [rainbow](#)

**Examples**

```
##We run an artificial example using the volcano data set as a study
##region
dim <- dim(volcano)
n.x <- dim[1]
n.y <- dim[2]

x <- 10 * 1:n.x
y <- 10 * 1:n.y

n.site <- 15
idx.x <- sample(n.x, n.site)
idx.y <- sample(n.y, n.site)
locations <- cbind(lon = x[idx.x], lat = y[idx.y])
alt <- diag(volcano[idx.x, idx.y])

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(40, locations, cov.mod = "whitmat", sill = 1, range = 750,
smooth = 1)

##Now define the spatial model for the GEV parameters
param.loc <- -10 - 0.04 * locations[,1] + alt / 5
param.scale <- 5 - locations[,2] / 30 + alt / 4
param.shape <- rep(.2, n.site)

##Transform the unit Frechet margins to GEV
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

##Define a model for the GEV margins to be fitted
##shape ~ 1 stands for the GEV shape parameter is constant
##over the region
loc.form <- loc ~ lon + alt
scale.form <- scale ~ lat + alt
shape.form <- shape ~ 1

## 1- Fit a max-stable process
schlather <- fitmaxstab(data, locations, "whitmat", loc.form, scale.form,
shape.form, marg.cov = cbind(alt = alt), sill =
1, std.err.type = "none")

## 2- Produce a map of the pointwise 50-year return level

##Here we have only one covariate i.e. alt
n.cov <- 1
covariates <- array(volcano, dim = c(n.x, n.y, n.cov), dimnames =
```

```
list(NULL, NULL, "alt"))

par(mfrow = c(1,2))
image(x, y, volcano, col = terrain.colors(64), main = "Elevation map")
map(schlather, x, y, covariates, ret.per = 50, plot.contour = FALSE,
main = "50-year return level")
```

---

map.latent

*Two dimensional map from a Bayesian hierarchical model*


---

## Description

This function plots 2D maps from a Markov chain.

## Usage

```
map.latent(fitted, x, y, covariates = NULL, param = "quant", ret.per =
100, col = terrain.colors(64), plot.contour = TRUE, fun = mean, level =
0.95, show.data = TRUE, control = list(nlines = 500), ...)
```

## Arguments

fitted	An object of class "latent". Typically this will be the output of <code>latent</code> .
x, y	Numeric vector specifying the coordinates of the grid points.
covariates	An array specifying the covariates at each grid point defined by x and y. If NULL, no covariate is needed.
param	A character string. Must be one of "loc", "scale", "shape" or "quant" for a map of the location, scale, shape parameters or for a map of a specified quantile.
ret.per	A numeric giving the return period for which the quantile map is plotted. It is only required if param = "quant".
col	A list of colors such as that generated by 'rainbow', 'heat.colors', 'topo.colors', 'terrain.colors' or similar functions.
plot.contour	Logical. If TRUE (default), contour lines are added to the plot.
fun	A character string specifying the function to be used to get posterior point estimates. The default is to take posterior means.
level	A numeric specifying the significance level for the pointwise credible intervals.
show.data	Logical. Should the locations where have observed the process have to be plotted?
control	A list with named components specifying options to be passed to <code>rgp</code> . Typically one might want specify <code>nlines</code> to reduce the computational demand.
...	Several arguments to be passed to the <code>link{image}</code> function.

## Value

A plot and a invisible list containing all the data required to do the plot.

## Author(s)

Mathieu Ribatet

**See Also**

[condrgp, map](#)

**Examples**

```
## Generate realizations from the model
n.site <- 30
n.obs <- 50
coord <- cbind(lon = runif(n.site, -10, 10), lat = runif(n.site, -10, 10))

gp.loc <- rgp(1, coord, "powexp", sill = 4, range = 20, smooth = 1)
gp.scale <- rgp(1, coord, "powexp", sill = 0.4, range = 5, smooth = 1)
gp.shape <- rgp(1, coord, "powexp", sill = 0.01, range = 10, smooth = 1)

locs <- 26 + 0.5 * coord[, "lon"] + gp.loc
scales <- 10 + 0.2 * coord[, "lat"] + gp.scale
shapes <- 0.15 + gp.shape

data <- matrix(NA, n.obs, n.site)
for (i in 1:n.site)
  data[,i] <- rgev(n.obs, locs[i], scales[i], shapes[i])

loc.form <- y ~ lon
scale.form <- y ~ lat
shape.form <- y ~ 1

hyper <- list()
hyper$sills <- list(loc = c(1,8), scale = c(1,1), shape = c(1,0.02))
hyper$ranges <- list(loc = c(2,20), scale = c(1,5), shape = c(1, 10))
hyper$smooths <- list(loc = c(1,1/3), scale = c(1,1/3), shape = c(1, 1/3))
hyper$betaMeans <- list(loc = rep(0, 2), scale = c(9, 0), shape = 0)
hyper$betaIcov <- list(loc = solve(diag(c(400, 100))),
                      scale = solve(diag(c(400, 100))),
                      shape = solve(diag(c(10), 1, 1)))

## We will use an exponential covariance function so the jump sizes for
## the shape parameter of the covariance function are null.
prop <- list(gev = c(2.5, 1.5, 0.2), ranges = c(0.7, 0.75, 0.9), smooths = c(0,0,0))
start <- list(sills = c(4, .36, 0.009), ranges = c(24, 17, 16), smooths
            = c(1, 1, 1), beta = list(loc = c(26, 0.5), scale = c(10, 0.2),
            shape = c(0.15)))

## Generate a Markov chain
mc <- latent(data, coord, loc.form = loc.form, scale.form = scale.form,
            shape.form = shape.form, hyper = hyper, prop = prop, start = start,
            n = 100)

x.grid <- y.grid <- seq(-10, 10, length = 50)
map.latent(mc, x.grid, y.grid, param = "shape")
```

## Description

These functions fit the generalised extreme value and generalised Pareto distribution to data using maximum likelihood.

## Usage

```
gevmlle(x, ..., method = "Nelder")
gpdmlle(x, threshold, ..., method = "Nelder")
```

## Arguments

x	Numeric vector of observations
...	Optional arguments to be passed to the <code>optim</code> function.
threshold	Numeric. The threshold value.
method	The numerical optimisation method to be used.

## Details

These two functions are “extremely light” functions to fit the GEV/GPD. These functions are mainly useful to compute starting values for the Schlather and Smith model - see [fitmaxstab](#).

If more refined (univariate) analysis have to be performed, users should use more specialised packages - e.g. POT, evd, ismev, ...

## Value

A vector for the estimated parameters of the GEV/GPD.

## Author(s)

Mathieu Ribatet

## Examples

```
## 1 - GEV fit
x <- rep(NA, 100)
for (i in 1:100)
  x[i] <- max(rnorm(365))

gevmlle(x)

## 2- GPD fit
x <- rnorm(10000)
##we need to fix a threshold
u <- quantile(x, 0.99)
gpdmlle(x, u)
```

---

`modeldef`*Define a model for the spatial behaviour of the GEV parameters*

---

## Description

This function defines the model for the spatial behaviour of the GEV parameter.

## Usage

```
modeldef(data, formula)
```

## Arguments

<code>data</code>	A matrix representing the data. Each column corresponds to one location.
<code>formula</code>	A R formula. See details for further details.

## Value

**need to be documented**

## Author(s)

Mathieu Ribatet

## See Also

[formula](#)

## Examples

```
## 1- A design matrix from a classical linear model
n.site <- 5
coord <- matrix(rnorm(2*n.site, sd = sqrt(.2)), ncol = 2)
colnames(coord) <- c("lon", "lat")
loc.form <- loc ~ lat + I(lon^2)
modeldef(coord, loc.form)

## 2- A design and penalization matrix from a penalized smoothin spline
x <- sort(runif(10, -2, 10))
n.knots <- 3
knots <- quantile(x, prob = 1:n.knots / (n.knots + 2))
modeldef(x, y ~ rb(x, knots = knots, degree = 3, penalty = 1))
```

---

`plot.maxstab`*Model checking of a fitted max-stable model*

---

## Description

This function produces several plots to assess the goodness of fit of a fitted max-stable model.

## Usage

```
## S3 method for class 'maxstab'  
plot(x, ..., sites)
```

## Arguments

<code>x</code>	An object of class <code>maxstab</code> . Most often, this will be the output of <code>fitmaxstab</code> or <code>lsmastab</code> .
<code>...</code>	Here for compatibility reasons but not yet implemented.
<code>sites</code>	A vector of integer of length 4 specifying the locations to be used for the model checking. If missing, locations will be chosen randomly.

## Details

The diagonal plots are return level plots. The lower ones are qq-plots (on the Gumbel scale) between observed pairwise maxima for each block, e.g. year, and the ones obtained by simulations from the fitted model. The upper plot compares the fitted extremal coefficient functions to semi-empirical estimates from the F-madogram - see `fmadogram`. The two remaining plots are the stations locations and a qq-plot of blockwise maxima where the block size is 4.

## Value

Several diagnostic plots.

## Author(s)

Mathieu Ribatet

## Examples

```
n.site <- 20  
n.obs <- 50  
coord <- matrix(runif(2 * n.site, 0, 10), ncol = 2)  
colnames(coord) <- c("lon", "lat")  
data <- rmaxstab(n.obs, coord, "powexp", sill = 1, range = 3, smooth =  
1)  
fitted <- fitmaxstab(log(data), coord, "powexp", y ~ 1, y ~ 1, y ~ 1,  
sill = 1)  
plot(fitted)
```

---

predict.maxstab      *Prediction of the max-stable marginal parameters*

---

### Description

This function predicts the marginal GEV parameters from a fitted max-stable process.

### Usage

```
## S3 method for class 'maxstab'
predict(object, newdata, ret.per = NULL, std.err =
TRUE, ...)
```

### Arguments

object	An object of class “maxstab”. Most often, it will be the output of the function <a href="#">fitmaxstab</a> .
newdata	An optional data frame in which to look for variables with which to predict. If omitted, the fitted values are used.
ret.per	Numeric vector giving the return periods for which return levels are computed. If NULL (default), no return levels are computed.
std.err	Logical. If TRUE (default), standard errors will be computed if possible.
...	further arguments passed to or from other methods.

### Value

‘predict.maxstab’ produces a vector of predictions or a matrix of predictions.

### Author(s)

Mathieu Ribatet

### See Also

[predict](#)

### Examples

```
## 1- Simulate a max-stable random field
n.site <- 35
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

data <- rmaxstab(50, locations, cov.mod = "whitmat", sill = 1, range = 30,
smooth = 0.5)

## 2- Transformation to non unit Frechet margins
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1]
param.shape <- rep(0.2, n.site)

for (i in 1:n.site)
```

```

    data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

## 3- Fit a max-stable process with the following model for
##    the GEV parameters
form.loc <- loc ~ lat
form.scale <- scale ~ lon
form.shape <- shape ~ 1

schlather <- fitmaxstab(data, locations, "whitmat", loc.form = form.loc,
                        scale.form = form.scale, shape.form =
                        form.shape)

## 4- GEV parameters estimates at each locations or at ungauged locations
predict(schlather)
ungauged <- data.frame(lon = runif(10, 0, 10), lat = runif(10, 0, 10))
predict(schlather, ungauged)

```

---

predict.pspline      *Prediction of smoothing spline with radial basis functions*

---

## Description

This function predicts the response from a fitted smoothing spline.

## Usage

```

## S3 method for class 'pspline'
predict(object, new.data, ...)

```

## Arguments

object	An object of class “pspline”. Most often, it will be the output of the function <a href="#">rbpspline</a> .
new.data	An optional data frame in which to look for variables with which to predict. If omitted, the fitted values are used.
...	further arguments passed to or from other methods.

## Value

‘predict.pspline’ produces a vector of predictions or a matrix of predictions.

## Author(s)

Mathieu Ribatet

## See Also

[predict](#)

**Examples**

```
## 1- Define a function to approximate
fun <- function(x)
  sin(3 * pi * x)

## 2- Compute the response from fun - and adding a noise
x <- seq(0, 1, length = 200)
y <- fun(x) + rnorm(200, 0, sqrt(0.4))

## 2- Fit a penalized smoothing spline
n.knots <- 30
knots <- quantile(x, prob = 1:n.knots / (n.knots + 2))
fitted <- rbpspline(y, x, knots, degree = 3)

## 3- Prediction from the fitted spline
plot(x, y, pch = 2, col = "red")
plot(fun, from = 0, to = 1, add = TRUE)
pred <- predict(fitted)
lines(pred[,1], pred[,2], col = "blue", pch = 3)
```

---

predict.spatgev      *Prediction of the GEV parameters*

---

**Description**

This function predicts the marginal GEV parameters from a fitted "spatial GEV" model.

**Usage**

```
## S3 method for class 'spatgev'
predict(object, newdata, ret.per = NULL, ...)
```

**Arguments**

object	An object of class spatgev". Most often, it will be the output of the function <code>fitspatgev</code> .
newdata	An optional data frame in which to look for variables with which to predict. If omitted, the fitted values are used.
ret.per	Numeric vector giving the return periods for which return levels are computed. If NULL (default), no return levels are computed.
...	further arguments passed to or from other methods.

**Value**

'predict.spatgev' produces a vector of predictions or a matrix of predictions.

**Author(s)**

Mathieu Ribatet

**See Also**[predict](#)**Examples**

```
## 1- Simulate a max-stable random field
n.site <- 35
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

data <- rmaxstab(50, locations, cov.mod = "whitmat", sill = 1, range = 3,
smooth = 0.5)
## 2- Transformation to non unit Frechet margins
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1]
param.shape <- rep(0.2, n.site)

for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

## 3- Fit a ''spatial GEV'' mdoel to data with the following models for
##   the GEV parameters
form.loc <- loc ~ lat
form.scale <- scale ~ lon
form.shape <- shape ~ 1

fitted <- fitspatgev(data, locations, form.loc, form.scale, form.shape)

## 4- GEV parameters estimates at each locations or at ungauged locations
predict(fitted)
ungauged <- data.frame(lon = runif(10, 0, 10), lat = runif(10, 0, 10))
predict(fitted, ungauged)
```

print.latent

*Printing objects of class "latent"***Description**

A method for printing object of class “maxstab”.

**Usage**

```
## S3 method for class 'latent'
print(x, digits = max(3, getOption("digits") - 3),
..., level = 0.95)
```

**Arguments**

x	An object of class “latent”. Most often, x is the output of the <a href="#">latent</a> function.
digits	The number of digits to be printed.
...	Other options to be passed to the <a href="#">print</a> function.
level	A numeric giving the significance level for the credible intervals.

**Value**

Print several information on screen.

**Author(s)**

Mathieu Ribatet

**Examples**

```
## Generate realizations from the model
n.site <- 15
n.obs <- 35
coord <- cbind(lon = runif(n.site, -10, 10), lat = runif(n.site, -10, 10))

gp.loc <- rgp(1, coord, "powexp", sill = 4, range = 20, smooth = 1)
gp.scale <- rgp(1, coord, "powexp", sill = 0.4, range = 5, smooth = 1)
gp.shape <- rgp(1, coord, "powexp", sill = 0.01, range = 10, smooth = 1)

locs <- 26 + 0.5 * coord[, "lon"] + gp.loc
scales <- 10 + 0.2 * coord[, "lat"] + gp.scale
shapes <- 0.15 + gp.shape

data <- matrix(NA, n.obs, n.site)
for (i in 1:n.site)
  data[,i] <- rgev(n.obs, locs[i], scales[i], shapes[i])

loc.form <- y ~ lon
scale.form <- y ~ lat
shape.form <- y ~ 1

hyper <- list()
hyper$sills <- list(loc = c(1,8), scale = c(1,1), shape = c(1,0.02))
hyper$ranges <- list(loc = c(2,20), scale = c(1,5), shape = c(1, 10))
hyper$smooths <- list(loc = c(1,1/3), scale = c(1,1/3), shape = c(1, 1/3))
hyper$betaMeans <- list(loc = rep(0, 2), scale = c(9, 0), shape = 0)
hyper$betaIcov <- list(loc = solve(diag(c(400, 100))),
                      scale = solve(diag(c(400, 100))),
                      shape = solve(diag(c(10), 1, 1)))

## We will use an exponential covariance function so the jump sizes for
## the shape parameter of the covariance function are null.
prop <- list(gev = c(2.5, 1.5, 0.2), ranges = c(0.7, 0.75, 0.9),
            smooths = c(0,0,0))
start <- list(sills = c(4, .36, 0.009), ranges = c(24, 17, 16), smooths
            = c(1, 1, 1), beta = list(loc = c(26, 0), scale = c(10, 0),
            shape = c(0.15)))

mc <- latent(data, coord, loc.form = loc.form, scale.form = scale.form,
            shape.form = shape.form, hyper = hyper, prop = prop, start = start,
            n = 500)

mc
```

---

print.maxstab      *Printing objects of class "maxstab"*

---

### Description

A method for printing object of class “maxstab”.

### Usage

```
## S3 method for class 'maxstab'  
print(x, digits = max(3, getOption("digits") - 3),  
      ...)
```

### Arguments

x	An object of class “maxstab”. Most often, x is the output of the <a href="#">fitmaxstab</a> function.
digits	The number of digits to be printed.
...	Other options to be passed to the <a href="#">print</a> function.

### Value

Print several information on screen.

### Author(s)

Mathieu Ribatet

### Examples

```
##Define the coordinates of each location  
n.site <- 30  
locations <- matrix(5 + rnorm(2*n.site, sd = sqrt(2)), ncol = 2)  
  
##Simulate a max-stable process - with unit Frechet margins  
data <- rmaxstab(30, locations, cov.mod = "whitmat", sill = 1, range = 3,  
smooth = 0.5)  
  
fit <- fitmaxstab(data, locations, "whitmat")  
fit
```

---

```
print.pspline
```

*Printing objects of class "pspline"*

---

**Description**

A method for printing object of class “pspline”.

**Usage**

```
## S3 method for class 'pspline'
print(x, ...)
```

**Arguments**

`x` An object of class “pspline”. Most often, `x` is the output of the `rbpspline` function.

`...` Other options to be passed to the `print` function.

**Value**

Print several information on screen.

**Author(s)**

Mathieu Ribatet

**Examples**

```
n <- 200
x <- runif(n)
fun <- function(x) sin(3 * pi * x)
y <- fun(x) + rnorm(n, 0, sqrt(0.4))
knots <- quantile(x, prob = 1:31 / 32)
fitted <- rbpspline(y, x, knots = knots, degree = 3)
fitted
```

---

```
print.spatgev
```

*Printing objects of class "spatgev"*

---

**Description**

A method for printing object of class “spatgev”.

**Usage**

```
## S3 method for class 'spatgev'
print(x, digits = max(3, getOption("digits") - 3),
...)
```

**Arguments**

<code>x</code>	An object of class "spatgev". Most often, <code>x</code> is the output of the <code>fitspatgev</code> function.
<code>digits</code>	The number of digits to be printed.
<code>...</code>	Other options to be passed to the <code>print</code> function.

**Value**

Print several information on screen.

**Author(s)**

Mathieu Ribatet

**Examples**

```
## 1- Simulate a max-stable random field
n.site <- 35
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

data <- rmaxstab(50, locations, cov.mod = "whitmat", sill = 1, range = 3,
smooth = 0.5)

## 2- Transformation to non unit Frechet margins
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1]
param.shape <- rep(0.2, n.site)

for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

## 3- Fit a 'spatial GEV' model to data with the following models for
## the GEV parameters
form.loc <- loc ~ lat
form.scale <- scale ~ lon
form.shape <- shape ~ 1

fitspatgev(data, locations, form.loc, form.scale, form.shape)
```

---

profile

*Method for profiling fitted max-stable objects*

---

**Description**

Computes profile traces for fitted max-stable models.

**Usage**

```
## S3 method for class 'maxstab'
profile(fitted, param, range, n = 10, plot = TRUE,
conf = 0.90, method = "RJ", square = "chol", ...)
```

**Arguments**

fitted	An object of class “maxstab”. Most often, it will be the output of the function <code>fitmaxstab</code> .
param	A character string giving the model parameter that are to be profiled.
range	The range for the profiled model parameter that must be explored.
n	Integer. The number of profiled model parameter that must be considered.
plot	Logical. If TRUE (default), the profile trace is plotted.
conf	Numeric giving the confidence interval level.
method	Character string. Must be one of "CB", "RJ" or "none" for the Chandler and Bate or the Rotnitzky and Jewell approaches respectively. The "none" method simply plots the profile of the log-composite likelihood. See details.
square	The choice for the matrix square root. This is only useful for the 'CB' method. Must be one of 'chol' (Cholesky) or 'svd' (Singular Value Decomposition).
...	Extra options that must be passed to the <code>plot</code> function.

**Details**

The Rotnitzky and Jewell approach consists in adjusting the distribution of the likelihood ratio statistics - which under misspecification is no longer  $\chi^2$  distributed.

The Chandler and Bate approach adjusts the composite likelihood itself in such a way that the usual asymptotic  $\chi^2$  null distribution is preserved. Note that in the current code, we use the singular value decomposition for the computation of matrix square roots to preserve asymmetry in the profile composite likelihood.

**Value**

A matrix. The first column corresponds to the values for which the profiled model parameter is fixed. The second column gives the value of the pairwise log-likelihood. The remaining columns contain the constrained maximum likelihood estimates for the remaining model parameters.

**Warnings**

This function can be **really** time consuming!

**Author(s)**

Mathieu Ribatet

**References**

Chandler, R. E. and Bate, S. (2007) Inference for clustered data using the independence loglikelihood *Biometrika*, **94**, 167–183.

Rotnitzky, A. and Jewell, N. (1990) Hypothesis testing of regression parameters in semiparametric generalized linear models for cluster correlated data. *Biometrika* **77**, 485–97.

**Examples**

```
## Not run:
##Define the coordinates of each location
n.site <- 30
locations <- matrix(rnorm(2*n.site, sd = sqrt(.2)), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 100, cov12 =
25, cov22 = 220)

##Fit a max-stable process
## 1- using the Smith's model
fitted <- fitmaxstab(data, locations, "gauss", fit.marge = FALSE)

##Plot the profile pairwise log-likelihood for the 'cov11' parameter
profile(fitted, "cov11", range = c(20, 180))

## End(Not run)
```

---

profile2d

---

*Method for profiling (in 2d) fitted max-stable objects*


---

**Description**

Computes profile surfaces for fitted max-stable models.

**Usage**

```
## S3 method for class 'maxstab'
profile2d(fitted, params, ranges, n = 10, plot = TRUE,
...)
```

**Arguments**

fitted	An object of class “maxstab”. Most often, it will be the output of the function <a href="#">fitmaxstab</a> .
params	A character vector giving the two model parameters that are to be profiled.
ranges	A matrix corresponding to the ranges for the profiled model parameters that must be explored. Each row corresponds to one model parameter range.
n	Integer. The number of profiled model parameter that must be considered.
plot	Logical. If TRUE (default), the profile surface is plotted.
...	Extra options that must be passed to the <a href="#">plot</a> function.

**Value**

A list with two arguments: `coord` and `llik`. `coord` is a matrix representing the grid where the profiled model parameters are fixed. `llik` the corresponding pairwise log-likelihood.

**Warnings**

This function can be **really** time consuming!

**Author(s)**

Mathieu Ribatet

**Examples**

```
## Not run:
##Define the coordinates of each location
n.site <- 30
locations <- matrix(rnorm(2*n.site, sd = sqrt(.2)), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(30, locations, cov.mod = "whitmat", sill = 1, range = 30,
smooth = 0.5)

##Now define the spatial model for the GEV parameters
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1] + locations[,2]^2
param.shape <- rep(0.2, n.site)

##Transform the unit Frechet margins to GEV
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i],
param.shape[i])

##Define a model for the GEV margins to be fitted
##shape ~ 1 stands for the GEV shape parameter is constant
##over the region
loc.form <- loc ~ lat
scale.form <- scale ~ lon + (lat^2)
shape.form <- shape ~ 1

##Fit a max-stable process
## 1- using the Schlather representation
fitted <- fitmaxstab(data, locations, "whitmat", loc.form, scale.form,
shape.form)

##Plot the profile pairwise log-likelihood for the smooth parameter
ranges <- rbind(c(9,11), c(.3, .8))
profile2d(fitted, c("range", "smooth"), ranges = ranges)

## End(Not run)
```

qqextcoeff

*QQ-plot for the extremal coefficient***Description**

This function compares the extremal coefficients estimated from a fitted max-stable process to the ones estimated semi-parametrically.

**Usage**

```
qqextcoeff(fitted, estim = "ST", marge = "emp", xlab = "Semi-Empirical",
ylab = "Model", ...)
```

**Arguments**

<code>fitted</code>	An object of class <code>maxstab</code> . Most often, this will be the output of <code>fitmaxstab</code> , <code>fitcovmat</code> or <code>fitcovariance</code> .
<code>estim, marge</code>	The <code>estim</code> and <code>marge</code> options to be passed to the <code>fitextcoeff</code> function.
<code>xlab, ylab</code>	The x and y-axis labels.
<code>...</code>	Optional arguments to be passed to the <code>plot</code> function.

**Value**

A QQ-plot.

**Author(s)**

Mathieu Ribatet

**References**

- Schlather, M. (2002) Models for Stationary Max-Stable Random Fields. *Extremes* **5**:1, 33–44.
- Schlather, M. and Tawn, J. A. (2003) A dependence measure for multivariate and spatial extreme values: Properties and inference. *Biometrika* **90**(1):139–156.
- Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

**See Also**

`fitmaxstab`, `fitextcoeff`

**Examples**

```
##Define the coordinate of each location
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 10, cov12 =
5, cov22 = 22)

fitted <- fitmaxstab(data, locations, "gauss")
qqextcoeff(fitted)
```

---

qqgev

*QQ-plot for the GEV parameters*

---

**Description**

This function compares the GEV parameters estimated separately for each location to the ones estimated from a fitted spatial model.

**Usage**

```
qqgev(fitted, xlab, ylab, ...)
```

**Arguments**

fitted	An object of class <code>maxstab</code> or <code>spatgev</code> . Most often, this will be the output of <code>fitmaxstab</code> , <code>fitcovmat</code> , <code>fitcovariance</code> or <code>fitspatgev</code> .
xlab, ylab	The x and y-axis labels. May be missing.
...	Optional arguments to be passed to the <code>plot</code> function.

**Value**

A QQ-plot.

**Author(s)**

Mathieu Ribatet

**References**

- Schlather, M. (2002) Models for Stationary Max-Stable Random Fields. *Extremes* **5**:1, 33–44.
- Schlather, M. and Tawn, J. A. (2003) A dependence measure for multivariate and spatial extreme values: Properties and inference. *Biometrika* **90**(1):139–156.
- Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

**See Also**

[qqextcoeff](#)

**Examples**

```
##Define the coordinate of each location
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(50, locations, cov.mod = "gauss", cov11 = 100, cov12 =
25, cov22 = 220)

##Now define the spatial model for the GEV parameters
param.loc <- -10 + 2 * locations[,2]
param.scale <- 5 + 2 * locations[,1] + locations[,2]^2
param.shape <- rep(0.2, n.site)

##Transform the unit Frechet margins to GEV
for (i in 1:n.site)
  data[,i] <- frech2gev(data[,i], param.loc[i], param.scale[i], param.shape[i])

##Define a model for the GEV margins to be fitted
##shape ~ 1 stands for the GEV shape parameter is constant
##over the region
loc.form <- loc ~ lat
scale.form <- scale ~ lon + I(lat^2)
shape.form <- shape ~ 1

fitted <- fitspatgev(data, locations, loc.form = loc.form, scale.form =
scale.form, shape.form = shape.form)
```

```
qqgev(fitted)
```

---

```
rainfall
```

---

*Summer annual maxima precipitation in Switzerland*

---

### Description

Maximum daily rainfall amounts over the years 1962–2008 occurring during June–August at 79 sites in Switzerland.

### Usage

```
data(rainfall)
```

### Format

This data set contains two R objects: 'rain' and 'coord'. 'rain' is a 47 by 79 matrix giving the amount of rain in millimeters, each column correspond to one locations. 'coord' is a 79 by 3 matrix giving the longitude, latitude and the elevation for each station, all of them being in meters.

### Author(s)

Mathieu Ribatet

### Examples

```
data(rainfall)
op <- par(mfrow = c(1,2),pty = "s", mar = c(0,0,0,0))
swiss(city = TRUE)
idx.site <- c(1, 10, 20)
points(coord[-idx.site,])
points(coord[idx.site,], pch = 15, col = 2:4)

par(mar = c(2,4,0,0))
plot(1962:2008, rain[,1], type = "b", xlab = "Year", ylab =
"Precipitation (cm)", ylim = c(0, 120), col = 2)
lines(1962:2008, rain[,10], col = 3, type = "b")
lines(1962:2008, rain[,20], col = 4, type = "b")
par(op)
```

---

```
rb
```

---

*Creates a model using penalized smoothing splines*

---

### Description

Creates a model using penalized smoothing splines using radial basis functions

### Usage

```
rb(..., knots, degree, penalty)
```

## Arguments

<code>...</code>	The explicative variables for which the spline is based on.
<code>knots</code>	The coordinates of knots. See section details.
<code>degree</code>	Numeric. The degree of the spline.
<code>penalty</code>	Numeric. The penalty coefficient.

## Details

If one explicative variable is given in "...", the `knots` should be a numeric vector. Otherwise, `knots` should be a matrix with the same number of column and covariates.

## Value

A list giving all the required information to fit a penalized smoothing spline:

<code>dsgn.mat</code>	The design matrix.
<code>pen.mat</code>	The penalization matrix.
<code>degree</code>	The degree of the smoothing spline.
<code>penalty</code>	The penalty of the smoothing spline.
<code>knots</code>	The knots of the smoothing spline.
<code>data</code>	The explicative variables (e.g. covariates).
<code>call</code>	How was the <code>rb</code> function was called?

## Warning

This function is not supposed to be called directly. `rb` is supposed to be embedded in a R formula.

## Author(s)

Mathieu Ribatet

## See Also

[fitmaxstab](#)

## Examples

```
n.site <- 30
locations <- matrix(runif(2*n.site, 0, 10), ncol = 2)
colnames(locations) <- c("lon", "lat")
knots <- quantile(locations[,2], 1:5/6)

form <- y ~ rb(lat, knots = knots, degree = 3, penalty = .5)
```

rbpspline

*Fits a penalized spline with radial basis functions to data***Description**

Fits a penalized spline with radial basis functions to data.

**Usage**

```
rbpspline(y, x, knots, degree, penalty = "gcv", ...)
```

**Arguments**

<code>y</code>	The response vector.
<code>x</code>	A vector/matrix giving the values of the predictor variable(s). If <code>x</code> is a matrix, each row corresponds to one observation.
<code>knots</code>	A vector giving the coordinates of the knots.
<code>degree</code>	The degree of the penalized smoothing spline.
<code>penalty</code>	A numeric giving the penalty coefficient for the penalization term. Alternatively, it could be either 'cv' or 'gcv' to choose the <code>penalty</code> using the (generalized) cross-validation criterion.
<code>...</code>	Additional options to be passed to the <code>cv</code> or <code>gcv</code> function.

**Details**

The penalized spline with radial basis is defined by:

$$f(x) = \beta_0 + \beta_1 x + \dots + \beta_{m-1} x^{m-1} + \sum_{k=0}^{K-1} \beta_{m+k} \|x - \kappa_k\|^{2m-1}$$

where  $\beta_i$  are the coefficients to be estimated,  $\kappa_i$  are the coordinates of the  $i$ -th knot and  $m = \frac{d+1}{2}$  where  $d$  corresponds to the `degree` of the spline.

The fitting criterion is to minimize

$$\|y - X\beta\|^2 + \lambda^{2m-1} \beta^T K \beta$$

where  $\lambda$  is the penalty coefficient and  $K$  the penalty matrix.

**Value**

An object of class `pspline`.

**Author(s)**

Mathieu Ribatet

**References**

Ruppert, D. Wand, M.P. and Carroll, R.J. (2003) *Semiparametric Regression* Cambridge Series in Statistical and Probabilistic Mathematics.

**See Also**[cv](#), [gcv](#)**Examples**

```
n <- 200
x <- runif(n)
fun <- function(x) sin(3 * pi * x)
y <- fun(x) + rnorm(n, 0, sqrt(0.4))
knots <- quantile(x, prob = 1:(n/4) / (n/4 + 1))
fitted <- rbpspline(y, x, knots = knots, degree = 3)
fitted

plot(x, y)
lines(fitted, col = 2)
```

rgp

*Gaussian Random Fields Simulation***Description**

This functions generates gaussian random fields.

**Usage**

```
rgp(n, coord, cov.mod = "powexp", mean = 0, nugget = 0, sill = 1, range
= 1, smooth = 1, grid = FALSE, control = list())
```

**Arguments**

<code>n</code>	Integer. The number of replications.
<code>coord</code>	The locations coordinates for which the gaussian process is observed.
<code>cov.mod</code>	Character string. The covariance model used. Must be one of "whitmat", "cauchy", "powexp" or "cauchy". See the <a href="#">covariance</a> function.
<code>mean</code>	Numeric. The mean of the gaussian random field.
<code>nugget</code>	Numeric. The nugget of the gaussian random field.
<code>sill</code>	Numeric. The sill parameter in the covariance function.
<code>range</code>	Numeric. The range parameter in the covariance function.
<code>smooth</code>	Numeric. The smooth parameter in the covariance function.
<code>grid</code>	Logical. Does <code>coord</code> defines a grid?
<code>control</code>	A named list with arguments 'nlines' (number of lines of the TBM simulation) and 'method' the name of the simulation method - must be one of 'exact', 'tbn' or 'circ'. If 'method' is NULL (default), the function tries to find the most appropriate simulation technique. If 'nlines' is NULL it is set to 1000.

**Value**

A matrix or an array containing the random field replicates.

**Author(s)**

Mathieu Ribatet

**See Also**`link{rmaxstab}`**Examples**

```
x <- y <- seq(0, 20, length = 100)
coord <- cbind(x, y)
gp <- rgp(1, coord, cov.mod = "whitmat", grid = TRUE)
filled.contour(x, y, gp, color.palette = terrain.colors)
```

rmaxstab

*Simulation of Max-Stable Random Fields***Description**

This functions generates realisation from a max-stable random field.

**Usage**

```
rmaxstab(n, coord, cov.mod = "gauss", grid = FALSE, control =
list(), ...)
```

**Arguments**

<code>n</code>	Integer. The number of observations.
<code>coord</code>	A vector or matrix that gives the coordinates of each location. Each row corresponds to one location - if any.
<code>cov.mod</code>	A character string that gives the max-stable model. This must be one of "gauss" for the Smith model or "whitmat", "cauchy", "powexp" and "bessel" for the Schlather model with the given correlation family.
<code>grid</code>	Logical. Does the coordinates represent grid points?
<code>control</code>	A named list with arguments 'nlines' (number of lines of the TBM simulation), 'method' the name of the simulation method - must be one of 'exact', 'tbn' or 'circ', and 'uBound' the uniform upper bound. See details.
<code>...</code>	The parameters of the max-stable model. See details.

**Details**

Users must supply the parameters for the max-stable model. For the Schlather model, users should supply the "sill", "range" and "smooth" parameter values. For the Smith model, if `coord` is univariate you must specify `var`, otherwise users should supply the covariance parameters i.e. parameters with names such as `cov11`, `cov12`, ...

Here are the details for each allowed components of 'control'. If 'method' is `NULL` (default), the function tries to find the most appropriate simulation technique. Current simulation techniques are a direct approach, i.e. Cholesky decomposition of the covariance matrix, the turning bands and the circular embedding methods. If 'nlines' is `NULL`, it is set to 1000. If 'uBound' is `NULL`, it is set to reasonable values - for example 3.5 for the Schlather model.

**Value**

A matrix containing observations from the required max-stable model. Each column represents one stations. If `grid = TRUE`, the function returns an array of dimension `nrow(coord) x nrow(coord) x n`.

**Author(s)**

Mathieu Ribatet

**References**

- Schlather, M. (2002) Models for Stationary Max-Stable Random Fields. *Extremes* 5:1, 33–44.  
 Smith, R. L. (1990) Max-stable processes and spatial extremes. Unpublished manuscript.

**See Also**

`fitmaxstab`

**Examples**

```
## 1. Smith's model
set.seed(8)
x <- y <- seq(0, 10, length = 100)
coord <- cbind(x, y)
data <- rmaxstab(1, coord, "gauss", cov11 = 9/8, cov12 = 0, cov22 = 9/8,
  grid = TRUE)
##We change to unit Gumbel margins for visibility
filled.contour(x, y, log(data), color.palette = terrain.colors)

## 2. Schlather's model
data <- rmaxstab(1, coord, cov.mod = "powexp", sill = 1, range = 3,
  smooth = 1, grid = TRUE)
filled.contour(x, y, log(data), color.palette = terrain.colors)
```

**Description**

The package **SpatialExtremes** aims to provide tools for the analysis of spatial extremes. Currently, the package uses the max-stable processes framework for the modelling of spatial extremes.

Max-stable processes are the extension of the extreme value theory to random fields. Consequently, they are good candidate to the analysis of spatial extremes. The strategy used in this package is to fit max-stable processes to data using composite likelihood.

In the future, the package will allow for non-stationarity as well as other approaches to model spatial extremes; namely latent variable and copula based approaches.

A package vignette has been written to help new users. It can be viewed, from the R console, by invoking `vignette("SpatialExtremesGuide")`.

## Details

The package provides the following main tools:

1. `rgp`: simulates gaussian random fields,
2. `rmaxstab`: simulates max-stable random fields,
3. `fitspatgev`: fits a spatial GEV model to data,
4. `fitmaxstab`, `lsmastab`: fits max-stable processes to data,
5. `latent`: draws a Markov chain from a Bayesian hierarchical model for spatial extremes,
6. `predict`: allows predictions for fitted max-stable processes,
7. `map`, `condmap`: plot a map for GEV parameter as well as return levels - or conditional return levels
8. `anova`, `TIC`, `DIC`: help users in model selection,
9. `madogram`, `fmadogram`, `lmadogram`: are (kind of) variograms devoted to extremes,
10. `fitextcoeff`: estimates semi-parametrically the extremal coefficient,
11. `extcoeff`: plots the evolution of the extremal coefficient from a fitted max-stable process,
12. `rbpspline`: fits a penalized spline with radial basis function,
13. `gev2frech`, `frech2gev`: transform GEV (resp. Frechet) observation to unit Frechet (resp. GEV) ones
14. `gevmle`, `gpdmle`: fit the GEV/GPD distributions to data,
15. `distance`: computes the distance between each pair of locations,
16. `profile`, `profile2d`: computes the profile composite likelihood,
17. `covariance`, `variogram`: computes the covariance/semivariogram function.

## Acknowledgement

The development of the package has been financially supported by the Competence Center Environment and Sustainability (CCES) and more precisely within the EXTREMES project (<http://www.cces.ethz.ch/projects/hazri/EXTREMES>).

## Author(s)

Mathieu Ribatet

---

swiss

*Map of the Switzerland.*

---

## Description

Plot a map of Switzerland and optionnaly some cities.

## Usage

```
swiss(city = FALSE, add = FALSE, axes = FALSE, km = TRUE, xlab = "",
      ylab = "", ...)
```

**Arguments**

<code>city</code>	Logical. If TRUE, some city are displayed. Default is to omit.
<code>add</code>	Logical. Should the map be added to an existing plot?
<code>axes</code>	Logical. Should the axis be displayed?
<code>km</code>	Logical. If TRUE (default) the longitude and latitude are expressed in kilometers. Otherwise it is in meters.
<code>xlab, ylab</code>	The x and y-axis labels.
<code>...</code>	Optional arguments to be passed to the <code>plot</code> function.

**Value**

A graphic window.

**Author(s)**

Dominik Schaub

**Examples**

```
swiss()
```

---

swissalt

*Elevation in Switzerland*

---

**Description**

Data required for plotting a Switzerland map with elevation.

**Usage**

```
data(swissalt)
```

**Format**

This data set contains three R objects. 'alt.mat' is a 192 by 115 matrix giving the elevation at the grid points defined by 'lon.vec' and 'lat.vec'.

**Author(s)**

Mathieu Ribatet

**Examples**

```
data(swissalt)

layout(matrix(c(1,2), 1), width = c(3.5,1))
mar <- rep(0, 4)
op <- par(mar = mar)
breaks <- seq(0, 2000, by = 250)
image(lon.vec, lat.vec, alt.mat, col = terrain.colors(length(breaks) - 1),
      xaxt = "n", yaxt = "n", bty = "n", xlab = "", ylab = "", xlim =
```

```

c(480, 840), ylim = c(58, 300))
swiss(add = TRUE, city = TRUE)

##Heat bar
mar <- c(3, 3, 3, 4)
par(las = 1, mar = mar)

plot.new()
plot.window(xlim = c(0, 1), ylim = range(breaks), xaxs = "i",
            yaxs = "i")
rect(0, breaks[-length(breaks)], 1, breaks[-1], col = terrain.colors(length(breaks) - 1),
     border = NA)
axis(4, at = breaks[-length(breaks)])
box()
title("Elevation\n(meters)")
par(op)

```

TIC

*Takeuchi's information criterion***Description**

Computes a the Takeuchi's information criterion which is equivalent to the AIC when the model is miss-specified.

**Usage**

```
TIC(object, ..., k = 2)
```

**Arguments**

object	An object of class <code>maxstab</code> or <code>spatgev</code> . Often, it will be the output of the <code>fitmaxstab</code> or <code>fitspatgev</code> function.
...	Additional objects of class <code>maxstab</code> or <code>spatgev</code> for which TIC should be computed.
k	Numeric. The penalty per parameter to be used. The case $k = 2$ (default) correspond to the classical TIC and $k = \log n$ , $n$ number of observations, is the robust version of the BIC.

**Details**

TIC is like AIC so that when comparing models one wants to get the lowest TIC score.

**Value**

Numeric.

**Author(s)**

Mathieu Ribatet

## References

- Gao, X. and Song, P. X.-K. (2009) Composite likelihood Bayesian information criteria for model selection in high dimensional data. Preprint.
- Sakamoto, Y., Ishiguro, M., and Kitagawa G. (1986) Akaike Information Criterion Statistics. D. Reidel Publishing Company.
- Varin, C. and Vidoni, P. (2005) A note on composite likelihood inference and model selection. *Biometrika* **92**(3):519–528.

## See Also

[fitmaxstab](#), [AIC](#)

## Examples

```
##Define the coordinate of each location
n.site <- 50
locations <- matrix(runif(2*n.site, 0, 100), ncol = 2)
colnames(locations) <- c("lon", "lat")

##Simulate a max-stable process - with unit Frechet margins
data <- rmaxstab(40, locations, cov.mod = "whitmat", sill = 0.8, range =
30, smooth = 0.5)

M0 <- fitmaxstab(data, locations, "powexp", std.err.type = "score",
fit.marge = FALSE)
M1 <- fitmaxstab(data, locations, "cauchy", std.err.type = "score",
fit.marge = FALSE)

TIC(M0, M1)
TIC(M0, M1, k = log(nrow(data)))
```

---

variogram

*Empirical variogram*

---

## Description

This function computes the empirical variogram.

## Usage

```
variogram(data, coord, n.bins, xlab, ylab, angles = NULL, add = FALSE,
xlim = c(0, max(dist)), ...)
```

## Arguments

- |                     |   |
|---------------------|---|
| <code>data</code>   | A matrix representing the data. Each column corresponds to one location.                    |
| <code>coord</code>  | A matrix that gives the coordinates of each location. Each row corresponds to one location. |
| <code>n.bins</code> | The number of bins to be used. If missing, pairwise madogram estimates will be computed.    |

<code>xlab, ylab</code>	The x-axis and y-axis labels. May be missing. Note that <code>ylab</code> must have the same length as <code>which</code> .
<code>angles</code>	A numeric vector. A partition of the interval $(0, \pi)$ to help detecting anisotropy.
<code>add</code>	Logical. If <code>TRUE</code> , the plot is added to the current figure; otherwise (default) a new plot is computed.
<code>xlim</code>	A numeric vector of length 2 specifying the x coordinate range.
<code>...</code>	Additional options to be passed to the <code>plot</code> function.

**Value**

A graphic and (invisibly) a matrix with the lag distances and the empirical variogram estimates.

**Author(s)**

Mathieu Ribatet

**See Also**

[fmadogram](#), [lmadogram](#)

**Examples**

```
n.site <- 20
n.obs <- 100
coord <- matrix(runif(2 * n.site, 0, 10), ncol = 2)
data <- rgp(n.obs, coord, "powexp", sill = 2, range = 3, smooth = 1)
variogram(data, coord)
```

---

vdc

*Van der Corput Sequence*


---

**Description**

This function generates the three dimensional Van der Corput sequence on the half unit Sphere of  $R^3$  - eventually randomly rotated.

**Usage**

```
vdc(n, rand.rot = FALSE)
```

**Arguments**

<code>n</code>	Integer. The length of the sequence.
<code>rand.rot</code>	Logical. Should the sequence be randomly rotated?

**Value**

A matrix giving the coordinates of the points in the half unit sphere.

**Author(s)**

Mathieu Ribatet

**References**

Freulon, X., de Fouquet, C., 1991. Remarques sur la pratique des bandes tournantes a trois dimensions. Cahiers de geostatistique, Fascicule 1, Centre de Geostatistique, Ecole des Mines de Paris, Fontainebleau, pp. 101–117.

**Examples**

vdc (10)

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